# Joint Spectra of Riemannian Manifolds with Rotational Symmetry 

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#### Abstract

We study the joint spectra and joint eigenfunctions of a family of commuting self-adjoint operators ( $\Lambda, X_{1}, \ldots, X_{\ell}$ ) on a compact, $n$ dimensional Riemannian manifold $M$. Here $\Lambda=\sqrt{-\Delta}$ (or a convenient perturbation), where $\Delta$ is the Laplace operator on $M$, and $X_{j}$ are first-order, self-adjoint, differential operators, or more generally pseudodifferential operators, on $M$. We concentrate on cases where $M$ has a group $G$ of isometries, especially when $G=S O(n)$, where we say $M$ has rotational symmetry.

Two basic cases are the flat 2 D torus $\mathbb{T}^{2}$ and the 2D sphere $S^{2}$, each with a natural $S O(2)$ action, yielding two commuting self-adjoint operators ( $\Lambda, X$ ). Classical analyses of their joint spectra and eigenfunctions, with emphasis on their differences, are reviewed in §1, and these results provide a springboard for more general studies pursued in subsequent sections, bringing in techniques from microlocal analysis to elucidate various spectral clustering and eigenfunction concentration effects that first appear in these two paradigm cases. Contact is made with earlier work, particularly [2], [5], and [9].


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## 1 Introduction

Let $M$ be a compact, connected, $n$-dimensional Riemannian manifold. Assume a compact Lie group $G$ acts effectively on $M$, as a group of isometries. Denote the action by $(g, x) \mapsto g x, g \in G, x \in M$.

A case of particular interest will be $G=S O(n)$, under the assumption that there exists $q \in M$ whose $G$-orbit $\mathcal{O}_{q}=\{g q: g \in G\}$ is a smooth submanifold of $M$, diffeomorphic to the standard sphere $S^{n-1} \subset \mathbb{R}^{n}$, via

$$
\begin{equation*}
\varphi_{q}: \mathcal{O}_{q} \longrightarrow S^{n-1} \tag{1.1}
\end{equation*}
$$

in such a way that $\varphi_{q}$ intertwines the $S O(n)$ action on $\mathcal{O}_{q}$ with the standard action of $S O(n)$ on $S^{n-1}$. Then we say $M$ has rotational symmetry.

Let $\Delta$ denote the Laplace-Beltrami operator on $M$. Then $L^{2}(M)$ has an orthonormal basis consisting of eigenfunctions of $\Delta$, belonging to eigenspaces

$$
\begin{equation*}
V_{\lambda}=\left\{u \in C^{\infty}(M): \Delta u=-\lambda^{2} u\right\}, \quad \lambda^{2} \in \operatorname{Spec}(-\Delta) \tag{1.2}
\end{equation*}
$$

The operator $\Delta$ commutes with the $S O(n)$ action on functions, given by

$$
\begin{equation*}
L(g) u(x)=u\left(g^{-1} x\right) \tag{1.3}
\end{equation*}
$$

Hence $L(g)$ leaves each eigenspace $V_{\lambda}$ invariant. We get a unitary representation $\pi_{\lambda}$ of $G$ on $V_{\lambda}$.

Typically the space $V_{\lambda}$ is not one-dimensional. We aim to bring in selfadjoint differential (or pseudodifferential) operators that commute with $\Delta$ (and with each other), arising from the $G$-action, and look at the joint spectrum of such a family of commuting self-adjoint operators, and also look at the behavior of the joint eigenfunctions of these operators.

To frame the study, we start with a look at two paradigm cases, when $n=2$, namely

$$
\begin{equation*}
M=S^{2}, \quad M=\mathbb{T}^{2} \tag{1.4}
\end{equation*}
$$

where $S^{2} \subset \mathbb{R}^{3}$ is the standard unit sphere and $\mathbb{T}^{2}=\mathbb{R}^{2} / 2 \pi \mathbb{Z}^{2}$ is a flat torus. In these cases, $G=S O(2) \approx \mathbb{T}^{1}$. The group $S O(2)$ acts on $S^{2}$ rotation about the $x_{3}$-axis, and $S O(2) \approx \mathbb{T}^{1}$ acts on $\mathbb{T}^{2}$ via

$$
\begin{equation*}
\varphi \cdot\left(\theta_{1}, \theta_{2}\right)=\left(\theta_{1}+\varphi, \theta_{2}\right), \tag{1.5}
\end{equation*}
$$

with addition in $\mathbb{R} / 2 \pi \mathbb{Z}$. We will describe results on eigenfunctions of $\Delta$ here, referring to Chapters 3 and 8 of [11] or Chapter 7 of [12] for details.

We start with $M=\mathbb{T}^{2}$, and take the $L^{2}$-inner product

$$
\begin{equation*}
(u, v)_{L^{2}}=(2 \pi)^{-2} \int_{\mathbb{T}^{2}} u(\theta) \overline{v(\theta)} d \theta \tag{1.6}
\end{equation*}
$$

Here an orthonormal basis is given by

$$
\begin{equation*}
e_{k}(\theta)=e^{i k \cdot \theta}, \quad k=\left(k_{1}, k_{2}\right) \in \mathbb{Z}^{2} \tag{1.7}
\end{equation*}
$$

and we have

$$
\begin{equation*}
\Delta e_{k}=-|k|^{2} e_{k}, \quad|k|^{2}=k_{1}^{2}+k_{2}^{2} \tag{1.8}
\end{equation*}
$$

We have differential operators

$$
\begin{equation*}
\partial_{j}: C^{\infty}\left(\mathbb{T}^{2}\right) \longrightarrow C^{\infty}\left(\mathbb{T}^{2}\right), \quad j=1,2, \tag{1.9}
\end{equation*}
$$

and

$$
\begin{equation*}
X_{j}=\frac{1}{i} \partial_{j} \Longrightarrow X_{j} e_{k}=k_{j} e_{k}, \quad k \in \mathbb{Z}^{2} \tag{1.10}
\end{equation*}
$$

The operator $X_{1}$ is derived from the $S O(2)$ action on $\mathbb{T}^{2}$ given by (1.5). The fact that $X_{2}$ commutes with both $\Delta$ and $X_{1}$ is in some sense serendipitous. We have $-\Delta=X_{1}^{2}+X_{2}^{2}$. For our considerations of joint spectra, we first have

$$
\begin{equation*}
\operatorname{Spec}\left(X_{1}, X_{2}\right)=\left\{\left(k_{1}, k_{2}\right): k_{j} \in \mathbb{Z}\right\}=\mathbb{Z}^{2} \tag{1.11}
\end{equation*}
$$

In place of considering the joint spectrum of $-\Delta$ and $X_{1}$, it is convenient to set

$$
\begin{equation*}
\Lambda=(-\Delta)^{1 / 2} \tag{1.12}
\end{equation*}
$$

so

$$
\begin{equation*}
\Lambda e_{k}=|k| e_{k} \tag{1.13}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{Spec}\left(\Lambda, X_{1}\right)=\left\{\left(\sqrt{k_{1}^{2}+k_{2}^{2}}, k_{1}\right):\left(k_{1}, k_{2}\right) \in \mathbb{Z}^{2}\right\} \tag{1.14}
\end{equation*}
$$

In addition, we have

$$
\begin{equation*}
\operatorname{Spec}\left(\Lambda, X_{1}, X_{2}\right)=\left\{\left(\sqrt{k_{1}^{2}+k_{2}^{2}}, k_{1}, k_{2}\right):\left(k_{1}, k_{2}\right) \in \mathbb{Z}^{2}\right\} \tag{1.15}
\end{equation*}
$$

The joint spectrum of $X_{1}$ and $X_{2}$, specified in (1.11), is the very regular integer lattice in $\mathbb{R}^{2}$. The triple joint spectrum specified in (1.15) is the lift of this lattice to a cone in $\mathbb{R}^{3}$. The set $\operatorname{Spec}\left(\Lambda, X_{1}\right)$, specified in (1.14), is an edge-on view of this spotted cone, depicted in Figure 1.1.


Figure 1.1: $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ on $\mathbb{T}^{2}$


Figure 1.2: Spherical coordinates on $S^{2}$

We now look at $S^{2}$. We use spherical coordinates $(\theta, \psi)$, defined by

$$
\begin{gather*}
x(\theta, \psi)=(\sin \theta \cos \psi, \sin \theta \sin \psi, \cos \theta) \\
0 \leq \theta \leq \pi, \quad 0 \leq \psi \leq 2 \pi \tag{1.16}
\end{gather*}
$$

illustrated in Figure 1.2.
In this case (cf. [12], (7.4.30)),

$$
\begin{equation*}
\operatorname{Spec}(-\Delta)=\left\{k^{2}+k: k \in \mathbb{Z}^{+}\right\} \tag{1.17}
\end{equation*}
$$

It is convenient to set

$$
\begin{equation*}
\Lambda=\left(-\Delta+\frac{1}{4}\right)^{1 / 2}-\frac{1}{2} \tag{1.18}
\end{equation*}
$$

so

$$
\begin{equation*}
\operatorname{Spec} \Lambda=\left\{k: k \in \mathbb{Z}^{+}\right\} \tag{1.19}
\end{equation*}
$$

and denote $-\lambda^{2}$-eigenspace of $\Delta$ by $V_{k}$, for $\lambda=\lambda_{k}=\sqrt{k^{2}+k}$ :

$$
\begin{equation*}
V_{k}=\left\{u \in C^{\infty}\left(S^{2}\right): \Lambda u=k u\right\} . \tag{1.20}
\end{equation*}
$$

Each eigenspace $V_{k}$ is seen to contain a 1-dimensional space of zonal harmonics,

$$
\begin{equation*}
\mathcal{Z}_{k}=\left\{u \in V_{k}: X_{1} u=0\right\} \tag{1.21}
\end{equation*}
$$

where $X_{1}$ is a first order differential operator with the property that $Y_{1}=$ $i X_{1}$ is a real vector field generating the $S O(2)$ action on $S^{2}$, i.e., rotation about the $x_{3}$-axis (of period $2 \pi$ ). The fact that $\operatorname{dim} \mathcal{Z}_{k}=1$ is established in Proposition 7.4.18 of [12]. (A different argument will be presented later on here, in §2.) Further calculations presented in [12] yield

$$
\begin{equation*}
\mathcal{Z}_{k}=\operatorname{Span}\left(Z_{k}\right) \tag{1.22}
\end{equation*}
$$

where

$$
\begin{equation*}
Z_{k}(\omega)=P_{k}(\cos \theta) \tag{1.23}
\end{equation*}
$$

for $\omega=x(\theta, \psi) \in S^{2}$, and $P_{k}(t)$ are Legendre polynomials, given by the generating function

$$
\begin{equation*}
\left(1-2 t r+r^{2}\right)^{-1 / 2}=\sum_{k=0}^{\infty} P_{k}(t) r^{k} \tag{1.24}
\end{equation*}
$$

To normalize this eigenfunction to have unit $L^{2}$-norm, one takes

$$
\begin{equation*}
Y_{k}^{0}(\omega)=\left(\frac{2 k+1}{4 \pi}\right)^{1 / 2} P_{k}(\cos \theta) \tag{1.25}
\end{equation*}
$$



Figure 1.3: $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ on $S^{2}$

Then (cf. [12], Proposition 7.4.35), an orthonormal basis of $V_{k}$ is given by

$$
\begin{equation*}
Y_{k}^{\ell}(\omega)=\alpha_{k \ell} e^{i \ell \psi} \sin ^{|\ell|} \theta P_{k}^{(|\ell|)}(\cos \theta), \quad|\ell| \leq k, \tag{1.26}
\end{equation*}
$$

where $\alpha_{k \ell}$ are normalizing constants. An alternative formula for this basis is

$$
\begin{equation*}
Y_{k}^{ \pm \ell}(\omega)=\alpha_{k \ell}\left(\omega_{1} \pm i \omega_{2}\right)^{\ell} P_{k}^{(\ell)}\left(\omega_{3}\right), \quad 0 \leq \ell \leq k \tag{1.27}
\end{equation*}
$$

We have

$$
\begin{equation*}
X_{1} Y_{k}^{\ell}=\ell Y_{k}^{\ell}, \quad \text { for } \quad|\ell| \leq k, \tag{1.28}
\end{equation*}
$$

and the joint spectrum of $\Lambda$ and $X_{1}$ is

$$
\begin{equation*}
\operatorname{Spec}\left(\Lambda, X_{1}\right)=\left\{(k, \ell) \in \mathbb{Z}^{+} \times \mathbb{Z}:|\ell| \leq k\right\} . \tag{1.29}
\end{equation*}
$$

We display this joint spectrum in Figure 1.3. Note similarities and differences in comparison with the display of $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ on $\mathbb{T}^{2}$, depicted in Figure 1.1.

Both figures display $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ for pairs $(\lambda, k)$ satisfying $0 \leq \lambda \leq 10$. The first figure has more spectral points, in large part because the area of $\mathbb{T}^{2}\left(4 \pi^{2}\right)$ exceeds the area of $S^{2}(4 \pi)$. Somewhat mitigating the ratio of the number of spectral points is the fact that all the joint spectra for $S^{2}$ are simple, as one can deduce from (1.26)-(1.28), while most joint spectral points for $\mathbb{T}^{2}$ are double. In fact, the joint spectra in (1.11) are simple, but the points $\left(k_{1}, k_{2}\right)$ and $\left(k_{1},-k_{2}\right) \in \mathbb{Z}^{2}$ from (1.11) have the same image in $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ in (1.14). Hence all the points $\left(\lambda, k_{1}\right) \in \operatorname{Spec}\left(\Lambda, X_{1}\right)$ in (1.14) have multiplicity 2 except for those for which $k_{1}=\lambda$. We will investigate the geometrical roots of this difference between having simple spectra and double spectra later on.

Another noticeable distinction between the two sets of joint spectra is their degree of regularity. For $S^{2}, \operatorname{Spec}\left(\Lambda, X_{1}\right)$ is simply that part of the lattice $\mathbb{Z}^{2}$ lying within the quadrant $\{(x, y): x \geq 0,|y| \leq x\}$. For $\mathbb{T}^{2}$, $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ lies in the same quadrant, but its points form a somewhat more elaborate pattern. One can make out families of points lying on branches of hyperbolas, but the spacing of the points is not even. For example, there is substantial clustering near the edges $y= \pm x$.

The more elaborate behavior of $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ on $\mathbb{T}^{2}$ is related to the notorious difficulty of the "lattice point problem," i.e., to the difficulty of precisely specifying the spectral counting function of $-\Delta$ on $\mathbb{T}^{2}$. In this connection, we observe that one has a similarly intricate spectral counting function for

$$
\begin{equation*}
\Lambda^{2}+X_{1}^{2} \text { on } S^{2} \tag{1.30}
\end{equation*}
$$

Note that $\Lambda^{2}+X_{1}^{2}$ is equal to

$$
\begin{equation*}
-\Delta+X_{1}^{2} \tag{1.31}
\end{equation*}
$$

modulo an element of $O P S^{1}\left(S^{2}\right)$. One might check out the spectral counting function of this operator.

We turn to the differences in the behavior of the joint eigenfunctions in these two cases. For $\mathbb{T}^{2}$, the eigenfunctions $e_{k}, k \in \mathbb{Z}^{2}$, all have absolute value 1 everywhere. As mentioned above, each joint eigenspace of $\left(\Lambda, X_{1}\right)$ has dimension 1 or 2 . In case $k_{2} \neq 0$, the $\left(\sqrt{k_{1}^{2}+k_{2}^{2}}, k_{1}\right)$ eigenspace is

$$
\begin{equation*}
\operatorname{Span}\left(e_{k_{1}, k_{2}}, e_{k_{1},-k_{2}}\right)=\left\{e^{i k_{1} \theta_{1}}\left(c_{1} e^{i k_{2} \theta_{2}}+c_{2} e^{-i k_{2} \theta_{2}}\right): c_{j} \in \mathbb{C}\right\} \tag{1.32}
\end{equation*}
$$

which does not display concentration or spiking effects. As for the eigenspaces $V_{\lambda}$ of $\Lambda$, it is the case that they can have arbitrarily large dimension (this is largely why the lattice counting problem is so hard), so a bit of spiking can occur. But such spiking does not occur for joint eigenfunctions of $\left(\Lambda, X_{1}\right)$.


Figure 1.4: Graphs of $y_{k}(\cos \theta)=Y_{k}^{0}(\omega),-\pi / 2 \leq \theta \leq \pi / 2$

We now look at joint eigenspaces of $\left(\Lambda, X_{1}\right)$ for $S^{2}$. As noted above, in this case each joint eigenspace has dimension 1 , and the ( $k, \ell$ )-eigenspace is spanned by the unit-norm eigenfunction $Y_{k}^{\ell}$. We start with the zonal harmonics $Y_{k}^{0}$, given by (1.25). One can produce graphs of these functions from computations of the Legendre polynomials $P_{k}(t)$. In turn, these polynomials satisfy the recursion relation

$$
\begin{equation*}
\frac{k+1}{2 k+1} P_{k+1}(t)=t P_{k}(t)-\frac{k}{2 k+1} P_{k-1}(t), \tag{1.33}
\end{equation*}
$$

cf. (7.4.292) of [12]. This is convenient for such a computation. Figure 1.4 illustrates the graphs of $Y_{k}^{0}(\omega)$ for $\omega_{3}=\cos \theta$, in cases $k=10,20$, and 30 .

Referring to Figure 1.2, we see that the graphs in Figure 1.4 yield graphs of $Y_{k}^{0}$ on the "northern hemisphere" of $S^{2}$. Now the polynomials $P_{k}(t)$ are even in $t$ for $k$ even and odd in $t$ for $k$ odd, so the zonal harmonics $Y_{k}^{0}(\omega)$ have the corresponding parity with respect to the inversion $\omega_{3} \mapsto-\omega_{3}$ about the "equator" of $S^{2}$.


Figure 1.5: $y_{30}(t)$ and the upper envelope $y=(1 / \pi)\left(1-t^{2}\right)^{-1 / 4}$

The graphs in Figure 1.4 illustrate the fact that the zonal harmonics $Y_{k}^{0}$ spike at the north and south poles of $S^{2}$. On the other hand, they do not concentrate at the poles; that is, their amplitudes do not tend to zero on any strip in $S^{2}$. In fact, in the limit as $k \rightarrow \infty$. the sequence of functions $y_{k}(t)$ has the upper envalope

$$
\begin{equation*}
y=\frac{1}{\pi}\left(1-t^{2}\right)^{-1 / 4} . \tag{1.34}
\end{equation*}
$$

See [7], $\S 4.8$ for a derivation of the large $k$ asymptotics of $P_{k}(t)$ that yield this. This phenomenon is illustrated in Figure 1.5.

We have distinguished between "spiking" and "concentration" and noted that the zonal harmonics $Y_{k}^{0}$ exhibit spiking but not concentration. Other eigenfunctions do exhibit concentration, as we will now illustrate with the eigenfunctions of highest "angular momentum"

$$
\begin{equation*}
Y_{k}^{k}(\omega)=\alpha_{k}\left(\omega_{1}+i \omega_{2}\right)^{k} \tag{1.35}
\end{equation*}
$$



Figure 1.6: Graphs of $w_{k}(\cos \theta)=\left|Y_{k}^{k}(\omega)\right|, \omega_{3}=\cos \theta, 0 \leq \theta \leq \pi$
satisfying

$$
\begin{equation*}
\left|Y_{k}^{k}(\omega)\right|^{2}=\left|\alpha_{k}\right|^{2}\left(1-\omega_{3}^{2}\right)^{k} \tag{1.36}
\end{equation*}
$$

or equivalently

$$
\begin{equation*}
\left|Y_{k}^{k}(\omega)\right|=w_{k}(\cos \theta), \quad w_{k}(t)=\left|\alpha_{k}\right|\left(1-t^{2}\right)^{k / 2} \tag{1.37}
\end{equation*}
$$

These eigenfunctions concentrate at the equator, $\theta=\pi / 2$, for $k$ large, as illustrated in Figure 1.6.

Extending this result, we will show that, for each $\beta \in(0,1)$, the set of eigenfunctions

$$
\begin{align*}
& \qquad\left\{Y_{k}^{\ell}(\omega): \frac{|\ell|}{k} \geq \sqrt{1-\beta^{2}}\right\} \\
& \text { concentrates on the strip }\left|\omega_{3}\right| \leq \beta  \tag{1.38}\\
& \text { as } k \longrightarrow \infty
\end{align*}
$$

Our approach to this will involve, not a study of the special functions arising in the formula (1.26), but rather general considerations, applicable to other


Figure 1.7: Surfaces of revolution, with and without poles
classes of $n$-dimensional manifolds with $S O(n)$-symmetry, bringing in tools from microlocal analysis. One such result, applicable specifically to the spherical harmonics on $S^{2}$, is given in Proposition 3.2 and the accompanying formulas (3.29)-(3.37). Concentration results for joint eigenfunctions in a much more general setting are given in Propositions 4.1-4.3.

The following observation illustrates a limitation on what sorts of sets spherical harmonics can concentrate on. Let $S_{ \pm}$denote the hemispheres $\left\{\omega \in S^{2}: \pm \omega_{3} \geq 0\right\}$. Then, as we will show in $\S 2$,

$$
\begin{equation*}
u \in V_{k} \Longrightarrow \int_{S_{ \pm}}|u|^{2} d S=\frac{1}{2}\|u\|_{L^{2}}^{2} \tag{1.39}
\end{equation*}
$$

In fact, thanks to the $S O(3)$-invariance of each eigenspace $V_{k}$, such an identity holds for all hemispheres $S_{ \pm}$of $S^{2}$. We will establish several generalizations of (1.39), both for higher dimensional spheres $S^{n}$ and for other classes of manifolds with $S O(n)$-symmetry. See Propositions 2.3-2.4.

We point out a couple of phenomena that drive the differences between the spectral behaviors of $\mathbb{T}^{2}$ and $S^{2}$. One is that the real vector fields $Y_{1}=i X_{1}$ have constant length on $\mathbb{T}^{2}$ but variable length on $S^{2}$. In fact, $Y_{1}$ vanishes at two points of $S^{2}$, the "north and south poles." This observation motivates a concept that will play a role in investigating conditions that yield simple joint spectra. Namely, let $M$ be a compact, connected, $n$ dimensional Riemannian manifold with $S O(n)$-symmetry, as introduced at the beginning of this introduction. We say $M$ has a pole at $p \in M$ provided

$$
\begin{equation*}
g p=p, \quad \forall g \in S O(n) \tag{1.40}
\end{equation*}
$$

and the derived action

$$
\begin{equation*}
D(g): T_{p} M \longrightarrow T_{p} M \tag{1.41}
\end{equation*}
$$

on the $n$-dimensional inner-product space $T_{p} M$ is equivalent to the standard action of $S O(n)$ on $\mathbb{R}^{n}$. In Figure 1.7 we display two surfaces of revolution in $\mathbb{R}^{3}$, one with a pair of poles, the other without poles.

The rest of this paper is organized as follows. In $\S 2$ we decompose $L^{2}(M)$ into mutually orthogonal pieces on which $G$ acts like copies of $\pi_{\alpha}$, where $\left\{\pi_{\alpha}: \alpha \in \mathcal{A}\right\}$ is a complete set of irreducible unitary representations of $G$. These pieces are the images of orthogonal projections $Q_{\alpha}$. We use these projections to decompose the eigenspaces $V_{\lambda}$ of $\Delta$,

$$
\begin{equation*}
V_{\lambda}=\bigoplus_{\alpha} V_{\lambda \alpha} \tag{1.42}
\end{equation*}
$$

noting that $Q_{\alpha}: V_{\lambda} \rightarrow V_{\lambda}$. We observe that, for $u \in L^{2}(M)$,

$$
\begin{equation*}
\int_{M} f|u|^{2} d V=\sum_{\beta} \int_{M} f\left|Q_{\beta} u\right|^{2} d V \tag{1.43}
\end{equation*}
$$

whenever $f \in L^{\infty}(M)$ is invariant under the $G$-action. This leads to an extension of (1.39), from $M=S^{2}$ (indeed, from $M=S^{n}$ ), to the setting where $M$ has an isometric involution $\iota$, commuting with the $G$-action, yielding

$$
\begin{equation*}
M=M_{+} \cup M_{-}, \quad \iota: M_{ \pm} \longrightarrow M_{\mp} \tag{1.44}
\end{equation*}
$$

with $M_{ \pm}$invariant under the $G$-action. Then (1.39) extends to

$$
\begin{equation*}
u \in V_{\lambda} \Longrightarrow \int_{M_{ \pm}}|u|^{2} d V=\frac{1}{2} \int_{M}|u|^{2} d V \tag{1.45}
\end{equation*}
$$

provided one has that

$$
\begin{equation*}
G=S O(n) \text { acts irreducibly on each space } V_{\lambda \alpha} . \tag{1.46}
\end{equation*}
$$

This is Proposition 2.3. We show in Proposition 2.4 that

$$
\begin{equation*}
\text { if } M \text { has a pole, then (1.46) holds. } \tag{1.47}
\end{equation*}
$$

In Proposition 2.8 we show that, if $M$ does not have a pole, but there is a $G$-orbit $\mathcal{O}_{q}$ as in (1.1), then, for each nonzero $V_{\lambda \alpha}$,

> the action of $S O(n)$ on $V_{\lambda \alpha}$ contains at most two irreducible components.

In $\S 3$, we focus our attention back on $M=S^{2}$, and examine the asymptotic behavior of

$$
\begin{equation*}
\int_{S^{2}} f|u|^{2} d S, \quad u \in V_{k}, \quad f \in C^{\infty}\left(S^{2}\right), \text { zonal. } \tag{1.49}
\end{equation*}
$$

In Proposition 3.2 we show that, if

$$
\begin{equation*}
u=\sum_{|\ell| \leq k} a_{\ell} Y_{k}^{\ell} \tag{1.50}
\end{equation*}
$$

then

$$
\begin{equation*}
\int_{S^{2}} f|u|^{2} d S=\sum_{|\ell| \leq k}\left|a_{\ell}\right|^{2} g\left(\frac{\ell}{k}\right)+R_{k}(u), \tag{1.51}
\end{equation*}
$$

where

$$
\begin{equation*}
\left|R_{k}(u)\right| \leq \frac{C}{k}\|u\|_{L^{2}}^{2}, \quad C=C(f), \tag{1.52}
\end{equation*}
$$

and

$$
\begin{equation*}
g(\lambda)=\frac{1}{\pi} \int_{-1}^{1} f_{0}\left(s \sqrt{1-\lambda^{2}}\right) \frac{d s}{\sqrt{1-s^{2}}}, \quad f(\omega)=f_{0}\left(\omega_{3}\right) . \tag{1.53}
\end{equation*}
$$

We show that $g \in C^{\infty}([-1,1])$ (perhaps despite appearances). For the special cases $u=Y_{k}^{0}$ and $u=Y_{k}^{k}$, one has, respectively,

$$
\begin{equation*}
\int_{S^{2}} f\left|Y_{k}^{0}\right|^{2} d S=\frac{1}{\pi} \int_{-1}^{1} f_{0}(s) \frac{d s}{\sqrt{1-s^{2}}}+O\left(k^{-1}\right) \tag{1.54}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{S^{2}} f\left|Y_{k}^{k}\right|^{2} d S=f_{0}(0)+O\left(k^{-1}\right) \tag{1.55}
\end{equation*}
$$

which can be compared, respectively, with the statement (1.34) about the upper envelope of $P_{k}(t)$ and the concentration analysis (1.37). Going further, we establish a version of (1.38), namely, for $\beta \in(0,1), \delta>0$,

$$
\begin{equation*}
\frac{|\ell|}{k} \geq \sqrt{1-\beta^{2}} \Longrightarrow \int_{\left|\omega_{3}\right| \geq \beta+\delta}\left|Y_{k}^{\ell}\right|^{2} d S \leq \frac{C(\delta)}{k} . \tag{1.56}
\end{equation*}
$$

We obtain sharper estimates, in more general settings, in §4.
To get the results (1.51)-(1.56), we do not delve into the analysis of $Y_{k}^{\ell}$ as special functions (as in (1.25)-(1.27)). Rather, we use methods of microlocal analysis. We start by writing (1.49) as

$$
\begin{equation*}
(\Pi(A) u, u)_{L^{2}}, \quad A u=f u \tag{1.57}
\end{equation*}
$$

where

$$
\begin{equation*}
\Pi(A)=\frac{1}{2 \pi} \int_{0}^{2 \pi} e^{-i t \Lambda} A e^{i t \Lambda} d t \tag{1.58}
\end{equation*}
$$

Egorov's theorem allows us to write $\Pi(A)$ as a pseudodifferential operator, in $O P S^{0}\left(S^{2}\right)$, and to specify its principal symbol. The operator $\Pi(A)$ commutes with both $\Lambda$ and the operator $X_{1}$ arising in (1.21). Using a functional calculus presented in [9], and developed further in Chapter 12 of [10] (see also [8], [2], for related developments), we show in Proposition 3.1 that

$$
\begin{equation*}
\Pi(A)=F_{0}\left(\Lambda, X_{1}\right)+R, \quad R \in O P S^{-1}\left(S^{2}\right) \tag{1.59}
\end{equation*}
$$

with

$$
\begin{equation*}
F_{0}\left(\Lambda, X_{1}\right)=g\left(\Lambda^{-1} X_{1}\right), \tag{1.60}
\end{equation*}
$$

and $g(\lambda)$ as in (1.53). This gives rise to the results (1.51)-(1.56).
The two-pronged goal of $\S 4$ is to extend and sharpen the estimate (1.56). In the expanded setting, $M$ is a compact, connected, $n$-dimensional Riemannian manifold, on which there is a vector field $Y$, which generates a 1-parameter group of isometries of $M$, so $X=i Y$ is self adjoint and commutes with $\Lambda=\sqrt{-\Delta}$. Then $V_{\lambda}$ splits into joint eigenspaces

$$
\begin{equation*}
V_{\lambda}=\bigoplus_{\mu} V_{\lambda \mu}, \quad V_{\lambda \mu}=\left\{u \in V_{\lambda}: X u=\mu u\right\} . \tag{1.61}
\end{equation*}
$$

As for the vector field $Y$, we assume

$$
\begin{equation*}
A_{0}=\min _{x \in M}|Y(x)|<\max _{x \in M}|Y(x)|=A_{1} . \tag{1.62}
\end{equation*}
$$

The role of the set $\left\{\omega \in S^{2}:\left|\omega_{3}\right| \geq \beta+\delta\right\}$ in (1.56) is expanded to

$$
\begin{equation*}
\Omega_{A}=\{x \in M:|Y(x)| \leq A\}, \quad \text { given } A \in\left(A_{0}, A_{1}\right) \tag{1.63}
\end{equation*}
$$

The role played by the condition on $(k, \ell)$ in (1.56) will be expanded by choosing

$$
\begin{equation*}
g \in C^{\infty}\left(\left[-A_{1}, A_{1}\right]\right), \quad g(\mu)=0 \text { for }|\mu| \leq A^{\prime}, \text { given } A^{\prime}>A . \tag{1.64}
\end{equation*}
$$

The extension and sharpening of (1.56) is then given by the following result, Proposition 4.3:

$$
\begin{align*}
& \text { if } f \in C^{\infty}(M), \operatorname{supp} f \subset \Omega_{A} \text {, then } \\
& u \in V_{\lambda \mu} \Rightarrow g\left(\frac{\mu}{\lambda}\right)\|f u\|_{C^{m}(M)} \leq \frac{C_{m}}{\lambda^{m}}\|u\|_{L^{2}}, \tag{1.65}
\end{align*}
$$

for each $m \in \mathbb{N}$. The key to this estimate again resides in the use of the functional calculus for commuting self-adjoint pseudodifferential operators. It is shown in Proposition 4.2 that, under the hypotheses above,

$$
\begin{equation*}
M_{f} g\left(\Lambda^{-1} X\right) \in O P S^{-\infty}(M) \tag{1.66}
\end{equation*}
$$

and this leads to (1.65).
The result (1.65) can be interpreted as implying that, for $u \in V_{\lambda \mu}$, with $|\mu / \lambda|>A^{\prime}, u$ concentrates on the set $M \backslash \Omega_{A}$, as $\lambda \rightarrow \infty$. Alternatively, we say $\Omega_{A}$ is a shadow region for such a family of eigenfunctions.

In $\S 5$ we retain the setting of $\S 4$, involving $M, \Lambda, X$, and examine Weyl asymptotics. In its basic form, this involves the counting function for the eigenvalues of $\Lambda$, repeatd according to multiplicity. This can be expressed in the form $\operatorname{Tr} \varphi_{\nu}(\Lambda)$, for a sequence of functions $\varphi_{\nu}: \mathbb{R}^{+} \rightarrow \mathbb{R}$, such as characteristic functions of $[0, \nu]$. It is convenient to take smoother functions, and deduce information on the counting functions via a Tauberian theorem. For example, one might start with heat asymptotics, Tr $e^{t \Delta}$, using $\varphi_{t}(\Lambda)=e^{-t \Lambda^{2}}, t \searrow 0$. More precise results arise via the use of wave equation techniques. One takes

$$
\begin{equation*}
\varphi \in \mathcal{S}(\mathbb{R}), \quad \varphi \geq 0, \quad \operatorname{supp} \hat{\varphi} \subset(-r, r), \quad r<\operatorname{Inj} M \tag{1.67}
\end{equation*}
$$

where $\operatorname{Inj} M$ is the injectivity radius, and considers

$$
\begin{equation*}
N_{\varphi}(R)=\operatorname{Tr} \varphi(\Lambda-R) \tag{1.68}
\end{equation*}
$$

One studies the asymptotic behavior of this as $R \rightarrow+\infty$. More generally, there are microlocal Weyl asymptotics, involving the behavior of

$$
\begin{equation*}
\operatorname{Tr} B \varphi(\Lambda-R), \quad B \in O P S^{0}(M) \tag{1.69}
\end{equation*}
$$

As in the classical work [6], this is analyzed by writing

$$
\begin{equation*}
B \varphi(\Lambda-R)=\int_{-\infty}^{\infty} B e^{i t(\Lambda-R)} \hat{\varphi}(t) d t \tag{1.70}
\end{equation*}
$$

and using a parametrix for the wave evolution operator $e^{i t \Lambda}$, for $|t|<r$. In particular, results of [6] give

$$
\begin{equation*}
N_{\varphi}(R) \sim C(\varphi, M) R^{n-1}, \quad R \rightarrow \infty \tag{1.71}
\end{equation*}
$$

Going further, we take

$$
\begin{equation*}
B=M_{f} h\left(\Lambda^{-1} X\right), \quad f \in C^{\infty}(M), h \in C^{\infty}\left(\left[-A_{1}, A_{1}\right]\right) \tag{1.72}
\end{equation*}
$$

and obtain the following, in Proposition 5.2:

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu, j} h\left(\frac{\mu}{\lambda}\right) \int_{M} f\left|u_{\lambda \mu j}\right|^{2} d V  \tag{1.73}\\
& =\int_{S^{*} M} f(x) h(\langle Y(x), \xi\rangle) d S(x, \xi)
\end{align*}
$$

where, for $(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X)$,

$$
\begin{equation*}
\left\{u_{\lambda \mu j}: 1 \leq j \leq \operatorname{dim} V_{\lambda \mu}\right\} \text { is an orthonormal basis of } V_{\lambda \mu} \tag{1.74}
\end{equation*}
$$

Specializing (1.74) to $f \equiv 1$ gives

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu} h\left(\frac{\mu}{\lambda}\right) \operatorname{dim} V_{\lambda \mu} \\
& =\int_{S^{*} M} h(\langle Y(x), \xi\rangle) d S(x, \xi) \tag{1.75}
\end{align*}
$$

We show in Lemma 5.4 that the last integral is equal to

$$
\begin{equation*}
\int_{I} h(y) \Psi(y) d y, \quad I=\left[-A_{1}, A_{1}\right], \tag{1.76}
\end{equation*}
$$

with $\Psi$ satisfying

$$
\begin{equation*}
\Psi=\Psi_{M, X} \in L^{1}(I, d y), \quad \Psi \geq 0, \quad \int_{I} \Psi(y) d y=1 . \tag{1.77}
\end{equation*}
$$

Having that the left side of (1.75) is given by (1.76), for $h \in C^{\infty}(I)$, we next have two tasks. First, we want to extend the validity of this identity to a larger class of functions $h$ on $I$, including functions that are piecewise continuous with a finite number of jumps. In fact, the extension goes further, to the situation where $h: I \rightarrow \mathbb{R}$ is a bounded function satisfying

$$
\begin{equation*}
h \in \mathcal{R}(I, \gamma), \quad \gamma=\Psi(y) d y \tag{1.78}
\end{equation*}
$$

that is to say, $h$ is Riemann integrable on the measured metric space $(I, \gamma)$. We expound on this concept in Appendix A.

We call the function $\Psi$ that arises in (1.76) the joint spectral clustering factor, and the second task we face after obtaining (1.75)-(1.77) is to analyze the behavior of this factor, and see how it depends on $M$ and $X$. In $\S 5$ we work through the examples $M=\mathbb{T}^{2}$ and $M=S^{2}$, obtaining

$$
\begin{equation*}
\Psi(y)=\frac{1}{\pi} \frac{1}{\sqrt{1-y^{2}}}, \quad y=[-1,1], \quad M=\mathbb{T}^{2} \tag{1.79}
\end{equation*}
$$

and

$$
\begin{equation*}
\Psi(y)=\frac{1}{2}, \quad y \in[-1,1], \quad M=S^{2} . \tag{1.80}
\end{equation*}
$$

This is a quantitative expression of what is behind the difference in appearance of the joint spectra of $(\Lambda, X)$, pictured in Figures 1.1 and 1.3, in these two cases.

In $\S 6$ we apply the results of (1.73)-(1.77), and also the shadowing results of $\S 4$, to additional examples of 2 D surfaces of revolution:
3. More general convex surfaces of revolution.
4. Symmetric dumbbell.
5. Top-heavy dumbbell.
6. Surface with inflective invariant geodesic.
7. Inner tube.
8. Surface with flattened equator.
9. Capped cylinder.

Illustrations of curves in $\mathbb{R}^{2}$ that produce such surfaces upon rotation about the $x_{3}$-axis are given in Figures 6.1-6.4. The first two of these figures also sketch the graphs of the factor $\Psi$ arising in Examples 4 and 5.

For surfaces in Example 3, the behavior of $\Psi$ is close to that of $S^{2}$; one has $\Psi \in C^{\infty}(I)$, though it is typically not constant. In the other examples, $\Psi$ has singularities, though in Examples 4-7 the singularities occur on the interior of $I$, rather than at the endpoints. In Examples 4-8, such singularities as occur are weaker than we see for $M=\mathbb{T}^{2}$ in (1.79). We have logarithmic singularities in Example 4, both log singularities and jumps in Example 5, power singularities with exponent $-1 / 6$ in Example 6, log singularities for the inner tube in Example 7, and power singularities with exponent $-1 / 4$ in Example 8. For the capped cylinder in Example 9, $\Psi$ has singularities of the same strength as (1.79).

Regarding the application of results on concentration and shadowing to these examples, we mention that, in Example 4 (the symmetric dumbbell), we show in Proposition 6.1 that there are eigenfunctions in $V_{\lambda \mu}$ that concentrate on small neighborhoods of the union of the two equators about the fattest parts of these dumbbells. However, thanks to results of $\S 2$, they cannot concentrate on a small neighborhood of just one of these equators, since each such eigenfunction is either even or odd under the associated involution $\iota$ on $M$ that arises here. We also have a result, Proposition 6.2, on the existence of pairs of elements of $\operatorname{Spec}(\Lambda, X)$ that are very close together, one associated to a joint eigenfunction that is even under the action of $\iota$, and one associated to an odd eigenfunction.

There are different conclusions to be reached about concentration and shadowing of joint eigenfunctions in Example 5, which the reader can check out.

This paper has two appendices. As already mentioned, Appendix A treats the notion of Riemann integrable functions on a compact, measured metric space, of relevance to extending (1.75)-(1.76) from $h \in C^{\infty}(I)$ to cases allowing $h$ to be discontinuous. Appendix B discusses the action of a finite symmetry group on eigenspaces. Results given here are relevant to Proposition 6.2, mentioned above.

## 2 Decomposition of the eigenspaces of $\Delta$

Let $M$ be a compact, connected, $n$-dimensional Riemannian manifold, with an $S O(n)$-action by isometries, as described in the opening paragraph of $\S 1$. Denote the eigenspaces of the Laplace operator on $M$ by

$$
\begin{equation*}
V_{\lambda}=\left\{u \in C^{\infty}(M): \Delta u=-\lambda^{2} u\right\}, \quad \lambda^{2} \in \operatorname{Spec}(-\Delta) . \tag{2.1}
\end{equation*}
$$

If $\pi_{\alpha}$ is an irreducible unitary representation of $S O(n)$, set

$$
\begin{equation*}
Q_{\alpha} u(x)=d_{\alpha} \int_{S O(n)} u\left(g^{-1} x\right) \overline{\chi_{\alpha}(g)} d g, \tag{2.2}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi_{\alpha}(g)=\operatorname{Tr} \pi_{\alpha}(g), \quad d_{\alpha}=\chi_{\alpha}(I) \tag{2.3}
\end{equation*}
$$

$I$ denoting the identity element of $S O(n)$. The operator $Q_{\alpha}$ is the orthogonal projection of $L^{2}(M)$ onto the subspace of $L^{2}(M)$ on which $L(g)$ acts like copies of $\pi_{\alpha}$, where

$$
\begin{equation*}
L(g) u(x)=u\left(g^{-1} x\right), \quad g \in S O(n) . \tag{2.4}
\end{equation*}
$$

Since $L(g)$ commutes with $\Delta$, so does $Q_{\alpha}$, so

$$
\begin{equation*}
Q_{\alpha}: V_{\lambda} \longrightarrow V_{\lambda} . \tag{2.5}
\end{equation*}
$$

We set

$$
\begin{equation*}
V_{\lambda \alpha}=Q_{\alpha}\left(V_{\lambda}\right), \tag{2.6}
\end{equation*}
$$

so we have an orthogonal decomposition

$$
\begin{equation*}
V_{\lambda}=\bigoplus_{\alpha \in \mathcal{A}_{\lambda}} V_{\lambda \alpha} \tag{2.7}
\end{equation*}
$$

where $\mathcal{A}_{\lambda}=\left\{\alpha: V_{\lambda \alpha} \neq 0\right\}$.
As one use of such a decomposition, we derive a simple but useful identity. Suppose $f \in L^{\infty}(M)$ is invariant under the $S O(n)$-action, so

$$
\begin{equation*}
M_{f} L(g)=L(g) M_{f}, \quad \forall g \in G=S O(n), \tag{2.8}
\end{equation*}
$$

where $M_{f} u=f u$. Hence

$$
\begin{equation*}
M_{f} Q_{\alpha}=Q_{\alpha} M_{f} \tag{2.9}
\end{equation*}
$$

Proposition 2.1 If $f \in L^{\infty}(M)$ is $S O(n)$-invariant and $u \in L^{2}(M)$, then

$$
\begin{equation*}
\int_{M} f|u|^{2} d V=\sum_{\beta} \int_{M} f\left|Q_{\beta} u\right|^{2} d V . \tag{2.10}
\end{equation*}
$$

Proof. The left side of (2.10) is equal to

$$
\begin{align*}
(f u, u) & =\sum_{\alpha, \beta}\left(f Q_{\alpha} u, Q_{\beta} u\right) \\
& =\sum_{\alpha, \beta}\left(Q_{\beta} M_{f} Q_{\alpha} u, Q_{\beta} u\right) \\
& =\sum_{\alpha, \beta}\left(M_{f} Q_{\beta} Q_{\alpha} u, Q_{\beta} u\right)  \tag{2.11}\\
& =\sum_{\beta}\left(M_{f} Q_{\beta} u, Q_{\beta} u\right),
\end{align*}
$$

where we have used $Q_{\beta}=Q_{\beta}^{2}=Q_{\beta}^{*} Q_{\beta}$ and $Q_{\alpha} Q_{\beta}=0$ for $\alpha \neq \beta$. The last quantity in (2.11) is equal to the right side of (2.10).

Corollary 2.2 In the setting of Proposition 2.1,

$$
\begin{equation*}
u \in V_{\lambda} \Rightarrow \int_{M} f|u|^{2} d V=\sum_{\beta \in \mathcal{A}_{\lambda}} \int_{M} f\left|Q_{\beta} u\right|^{2} d V \tag{2.12}
\end{equation*}
$$

One can deduce the identity (1.39) from (2.12). Here is a natural generalization.

Proposition 2.3 Take $M$ as above, and assume there is an isometric involution

$$
\begin{equation*}
\iota: M \longrightarrow M, \quad \text { commuting with the action of } G=S O(n), \tag{2.13}
\end{equation*}
$$

such that

$$
\begin{equation*}
M=M_{+} \cup M_{-}, \quad \iota: M_{ \pm} \longrightarrow M_{\mp}, \tag{2.14}
\end{equation*}
$$

with

$$
\begin{equation*}
M_{ \pm} \text {invariant under the G-action. } \tag{2.15}
\end{equation*}
$$

In addition, assume

$$
\begin{equation*}
G=S O(n) \text { acts irreducibly on } V_{\lambda \alpha} \text {, for each } \alpha \in \mathcal{A}_{\lambda} . \tag{2.16}
\end{equation*}
$$

Then

$$
\begin{equation*}
u \in V_{\lambda} \Rightarrow \int_{M_{ \pm}}|u|^{2} d V=\frac{1}{2} \int_{M}|u|^{2} d V . \tag{2.17}
\end{equation*}
$$

Proof. By (2.13), $\iota^{*}: V_{\lambda \alpha} \rightarrow V_{\lambda \alpha}$, and, if (2.16) holds,

$$
\begin{equation*}
\iota^{*}= \pm 1 \text { on each space } V_{\lambda \alpha} . \tag{2.18}
\end{equation*}
$$

Now we can apply (2.12) with $f=\chi_{M_{ \pm}}$, to get, for $u \in V_{\lambda}$,

$$
\begin{equation*}
\int_{M_{ \pm}}|u|^{2} d V=\sum_{\alpha \in \mathcal{A}_{\lambda_{M}}} \int_{M_{ \pm}}\left|Q_{\alpha} u\right|^{2} d V . \tag{2.19}
\end{equation*}
$$

But (2.18) implies

$$
\begin{equation*}
\int_{M_{ \pm}}\left|Q_{\alpha} u\right|^{2} d V=\frac{1}{2} \int_{M}\left|Q_{\alpha} u\right|^{2} d V, \quad \forall \alpha \in \mathcal{A}_{\lambda}, \tag{2.20}
\end{equation*}
$$

whenever $u \in V_{\lambda}$, so (2.19) is equal to

$$
\begin{equation*}
\frac{1}{2} \sum_{\alpha \in \mathcal{A}_{\lambda}} \int_{M}\left|Q_{\alpha} u\right|^{2} d V=\frac{1}{2} \int_{M}|u|^{2} d V, \tag{2.21}
\end{equation*}
$$

again by (2.12), with $f \equiv 1$. This gives the asserted conclusion (2.17).
The applicability of Proposition 2.3 to the identity (1.39) follows from the fact that each joint eigenspace of $\left(\Lambda, X_{1}\right)$ on $S^{2}$ is one-dimensional, spanned by $Y_{k}^{\ell}$, given by (1.26)-(1.27), so clearly the $S O(2)$ action on such a space is irreducible. Here is a more general irreducibility result, applicable to $n$ dimensional $S O(n)$-symmetric manifolds with a pole (including, of course, $\left.M=S^{n}\right)$.

Proposition 2.4 Let $M$ be a compact, connected, n-dimensional Riemannian manifold ( $n \geq 2$ ) with an $S O(n)$-action by isometries. Assume $M$ has a pole at $p$. Then

$$
\begin{equation*}
G=S O(n) \text { acts irreducibly on } V_{\lambda \alpha} \text {, for each } \alpha \in \mathcal{A}_{\lambda} \text {. } \tag{2.22}
\end{equation*}
$$

We get started with the following special case.

Lemma 2.5 Take $M$ as in Proposition 2.4, and, for $\lambda^{2} \in \operatorname{Spec}(-\Delta)$, consider

$$
\begin{equation*}
V_{\lambda 0}=\left\{u \in V_{\lambda}: L(g) u=u, \forall g \in S O(n)\right\} . \tag{2.23}
\end{equation*}
$$

Then

$$
\begin{equation*}
\operatorname{dim} V_{\lambda 0} \leq 1 \tag{2.24}
\end{equation*}
$$

Our approach to the proof of this makes use of the following.
Lemma 2.6 Take $M, \lambda$ as in Lemma 2.5. Then there exists $r_{1}=r_{1}(\lambda)>0$ such that

$$
\begin{equation*}
u \in V_{\lambda}, r \in\left(0, r_{1}\right],\left.u\right|_{\partial B_{r}(p)}=0 \Longrightarrow u \equiv 0 \tag{2.25}
\end{equation*}
$$

Proof. If $\mu=\mu(r)$ denotes the smallest eigenvalue of $-\Delta$ on the ball $B_{r}(p)$, with the Dirichlet boundary condition on its boundary $\partial B_{r}(p)$, we have the variational characterization

$$
\begin{equation*}
\mu(r)=\inf \left\{\int_{B_{r}(p)}|\nabla v|^{2} d V: v \in C_{0}^{\infty}\left(B_{r}(p)\right),\|v\|_{L^{2}}=1\right\} \tag{2.26}
\end{equation*}
$$

and, as is classical,

$$
\begin{equation*}
\mu(r) \nearrow+\infty, \text { as } r \searrow 0 . \tag{2.27}
\end{equation*}
$$

As soon as $\mu\left(r_{1}\right)>\lambda^{2}$, we have that the hypotheses of (2.25) imply

$$
\begin{equation*}
u=0 \quad \text { on } B_{r}(p), \tag{2.28}
\end{equation*}
$$

and then unique continuation for solutions to $\left(\Delta+\lambda^{2}\right) u=0$ implies $u \equiv 0$ on $M$.

Proof of Lemma 2.5. Assume $V_{\lambda 0} \neq 0$. Pick $u, v \in V_{\lambda 0}$, both $\neq 0$. Take $r_{1}=r_{1}(\lambda)$ as in Lemma 2.6. Both $u$ and $v$ are constant on $\partial B_{r_{1}}(p)$, so there exist nonzero constants $a_{j} \in \mathbb{C}$ such that

$$
\begin{equation*}
a_{1} u+a_{2} v=0 \quad \text { on } \partial B_{r_{1}}(p) \tag{2.29}
\end{equation*}
$$

By Lemma 2.6, this implies $a_{1} u+a_{2} v \equiv 0$ on $M$, hence $\operatorname{dim} V_{\lambda 0}=1$.
Before proceeding to Proposition 2.4, we note that Lemma 2.5 leads to the following classical result.

Corollary 2.7 Take $M=S^{n}$, and assume $n \geq 2$. Then the isometry group $S O(n+1)$ acts irreducibly on each eigenspace $V_{\lambda}$ of $\Delta$.

Proof. Note that the $S O(n+1)$ action commutes with $\Delta$, so $S O(n+1)$ acts on each eigenspace $V_{\lambda}$. Suppose $W \subset V_{\lambda}$ is a linear subspace that is invariant under this action, and we take a nonzero $w \in W$. There exists $q \in S^{n}$ such that $w(q) \neq 0$, and there exists $g \in S O(n+1)$ such that $g q=p$, the "north pole" of $S^{n}$. Hence $L(g) w=w_{1} \in W$ and $w_{1}(p) \neq 0$. Now form

$$
\begin{equation*}
w_{2}=\int_{S O(n)} L(g) w_{1} d g, \tag{2.30}
\end{equation*}
$$

so

$$
\begin{equation*}
w_{2} \in W \cap V_{\lambda 0}, \quad w_{2}(p)=w_{1}(p) \neq 0 \tag{2.31}
\end{equation*}
$$

Now, if $W \neq V_{\lambda}$, let $W^{\perp} \subset V_{\lambda}$ denote its orthogonal complement, and take a nonzero $v \in W^{\perp}$. The same argument as above yields

$$
\begin{equation*}
v_{2} \in W^{\perp} \cap V_{\lambda 0}, \quad v_{2} \neq 0 . \tag{2.32}
\end{equation*}
$$

Then Lemma 2.5 implies $v_{2}$ is a scalar multiple of $w_{2}$, contradicting the fact that $v_{2} \perp w_{2}$. This contradiction implies $W=V_{\lambda}$, and we have the asserted irreducibility.

We now tackle Proposition 2.4. We divide the proof into two parts.
Proof of Proposition 2.4 when $n=2$. In this case, the action of $G=$ $S O(2)$ is given by the flow $\mathcal{F}_{Y_{1}}^{t}$, generated by a real vector field $Y_{1}$, periodic of period $2 \pi$. The self adjoint operator $X_{1}=(1 / i) Y_{1}$ commutes with $\Lambda=$ $(-\Delta)^{1 / 2}$. The spaces $V_{\lambda \alpha}$ become

$$
\begin{equation*}
V_{\lambda k}=\left\{u \in V_{\lambda}: X_{1} u=k u\right\}, \quad k \in \mathcal{A}_{\lambda} \subset \mathbb{Z} \tag{2.33}
\end{equation*}
$$

We are asserting that $\operatorname{dim} V_{\lambda k}=1$ for each $k \in \mathcal{A}_{\lambda}$. The proof is similar to that of Lemma 2.5. Pick $u, v \in V_{\lambda k}$, both $\neq 0$. Take $r_{1}=r_{1}(\lambda)$ as in Lemma 2.6. If we fix $q \in \partial B_{r_{1}}(p)$, both $u$ and $v$, restricted to $\partial B_{r_{1}}(p)$, are constant multiples of the function $\varphi_{k}$ defined by

$$
\begin{equation*}
\varphi_{k}\left(\mathcal{F}_{Y_{1}}^{t} q\right)=e^{i k t} \tag{2.34}
\end{equation*}
$$

Thus there exist constants $a_{j} \in \mathbb{C}$ such that $a_{1} u+a_{2} v=0$ on $\partial B_{r_{1}}(p)$. By Lemma 2.6, this implies $a_{1} u+a_{2} v \equiv 0$ on $M$, so $\operatorname{dim} V_{\lambda k}=1$.

Proof of Proposition 2.4 when $n \geq 3$. Note that the representation $\pi_{\alpha}$
of $S O(n)$ must be contained in the standard action of $S O(n)$ on $L^{2}\left(S^{n-1}\right)$. Assume $W \subset V_{\lambda \alpha}$ is a linear subspace, invariant under the $S O(n)$-action, and take a nonzero $u \in W$. Take $r_{1}=r_{1}(\lambda)$ as in Lemma 2.6, and set $S_{r}=\partial B_{r}(p)$. We see that for each $r \in\left(0, r_{1}\right],\left.u\right|_{S_{r}}$ is not $\equiv 0$. Fix $q \in S_{r_{1}}$. There exists $g \in S O(n)$ such that $u_{1}=L(g) u$ is nonvanishing at $q$. Also, of course, $u_{1} \in W$. Identifying $S O(n-1)$ with the subgroup of $S O(n)$ fixing $q$, set

$$
\begin{equation*}
u_{2}=\int_{S O(n-1)} L(g) u_{1} d g, \tag{2.35}
\end{equation*}
$$

so

$$
\begin{equation*}
u_{2} \in W, \quad u_{2}(q)=u_{1}(q) \neq 0 . \tag{2.36}
\end{equation*}
$$

Now $\varphi_{2}=\left.u_{2}\right|_{r_{r_{1}}}$ is an element of $C^{\infty}\left(S_{r_{1}}\right) \approx C^{\infty}\left(S^{n-1}\right)$ in the subspace on which

$$
\begin{equation*}
\{L(g): g \in S O(n)\} \quad \text { acts like } \pi_{\alpha}, \tag{2.37}
\end{equation*}
$$

and $S O(n-1)$ acts trivially on $\varphi_{2}$. The argument used in the proof of Corollary 2.7 implies the space (2.37) has just a 1 -dimensional subspace on which $S O(n-1)$ acts trivially (space of "zonal harmonics"), so $\varphi_{2}$ must span this space.

Now, if $W \neq V_{\lambda \alpha}$, then its orthogonal complement $W^{\perp} \subset V_{\lambda \alpha}$ contains a nonzero element, and by the argument above we have

$$
\begin{equation*}
v_{2} \in W^{\perp}, \quad v_{2} \neq 0, \quad v_{2} \text { invariant under the } S O(n-1) \text {-action. } \tag{2.38}
\end{equation*}
$$

Since the restrictions of both $w_{2}$ and $v_{2}$ to $S_{r_{1}}$ are both zonal functions in the same irreducible component of the $S O(n)$ action on $L^{2}\left(S_{r_{1}}\right)$, we have $a_{j} \in \mathbb{C}$ such that

$$
\begin{equation*}
a_{1} u_{2}+a_{2} v_{2}=0 \quad \text { on } S_{r_{1}}=\partial B_{r_{1}}(p) . \tag{2.39}
\end{equation*}
$$

It follows from Lemma 2.6 that

$$
\begin{equation*}
a_{1} u_{2}+a_{2} v_{2} \equiv 0 \quad \text { on } \quad M . \tag{2.40}
\end{equation*}
$$

This contradicts the fact that $u_{2} \perp v_{2}$, so $W=V_{\lambda \alpha}$, and we have the asserted irreducibility.

In cases where there is not a pole, we have the following variant of Proposition 2.4.

Proposition 2.8 Let $M$ be a compact, connected, n-dimensional Riemannian manifold, with an $S O(n)$-action by isometries. Assume there is a point $q \in M$ whose orbit

$$
\begin{equation*}
\mathcal{O}_{q}=\{g q: g \in S O(n)\} \tag{2.41}
\end{equation*}
$$

is a smooth submanifold of $M$, diffeomorphic to $S^{n-1}$, as in (1.1), in such a way that $\varphi_{q}$ intertwines the $S O(n)$ action on $\mathcal{O}_{q}$ with the standard action of $S O(n)$ on $S^{n-1}$. Then, for $\lambda^{2} \in \operatorname{Spec}(-\Delta), \alpha \in \mathcal{A}_{\lambda}$,

$$
\begin{equation*}
\text { the action of } S O(n) \text { on } V_{\lambda \alpha} \text { contains } \tag{2.42}
\end{equation*}
$$

at most two irreducible components.
In preparation for proving this, we bring in a variant of Lemma 2.6. For $r>0$, let

$$
\begin{equation*}
\Omega_{r}=\left\{x \in M: \operatorname{dist}\left(x, \mathcal{O}_{q}\right)<r\right\} . \tag{2.43}
\end{equation*}
$$

Then there exists $r_{0}>0$ such that, for $r \in\left(0, r_{0}\right], \partial \Omega_{r}$ consists of two $S O(n)$ orbits, each diffeomorphic to $S^{n-1}$, like $\mathcal{O}_{q}$ in (2.41). The following variant of Lemma 2.6 has a similar proof.

Lemma 2.9 Take $M, \lambda$ as in Proposition 2.8, and construct $\Omega_{r}$ as above. Then there exists $r_{1}=r_{1}(\lambda) \in\left(0, r_{0}\right]$ such that

$$
\begin{equation*}
u \in V_{\lambda}, r \in\left(0, r_{1}\right],\left.u\right|_{\partial \Omega_{r}}=0 \Longrightarrow u \equiv 0 \tag{2.44}
\end{equation*}
$$

Proof of Proposition 2.8. We concentrate on the case $n \geq 3$. Suppose

$$
\begin{equation*}
V_{\lambda \alpha}=W_{1} \oplus W_{2} \oplus W_{3} \tag{2.45}
\end{equation*}
$$

is an orthogonal decomposition, with each $W_{j}$ invariant under the $S O(n)$ action, and suppose $u_{j} \in W_{j}, u_{j} \neq 0$. Hence, for each $j,\left.u_{j}\right|_{\partial \Omega_{r_{1}}}$ is not $\equiv 0$.

Denote by $S O(n-1)$ the subgroup of $S O(n)$ fixing $q$. This subgroup also fixes the points on the geodesic $\gamma$ through $q$ that is orthogonal to $\mathcal{O}_{q}$, and it hence fixes the nearby points $q_{ \pm}$on the two components $\partial_{ \pm}$of $\partial \Omega_{r_{1}}$ where $\gamma$ intersects the boundary of $\Omega_{r_{1}}$. One can take $g_{j} \in S O(n)$ such that, for each $j, v_{j}=L\left(g_{j}\right) u_{j}$ does not vanish identically on $\left\{q_{ \pm}\right\}$, so

$$
\begin{equation*}
w_{j}=\int_{S O(n-1)} L(g) v_{j} d g \tag{2.46}
\end{equation*}
$$

satisfies

$$
\begin{equation*}
w_{j} \in W_{j},\left.\quad w_{j}\right|_{\partial \Omega_{r_{1}}} \neq 0, \tag{2.47}
\end{equation*}
$$

and each $w_{j}$ is invariant under the $S O(n-1)$ action.
Now we have the trace map

$$
\begin{equation*}
\tau: C^{\infty}(M) \longrightarrow C^{\infty}\left(\partial_{+}\right) \oplus C^{\infty}\left(\partial_{-}\right) \tag{2.48}
\end{equation*}
$$

and the image under $\tau$ of $\operatorname{Span}\left(w_{1}, w_{2}, w_{3}\right)$ is contained in a two-dimensional subspace of $C^{\infty}\left(\partial_{+}\right) \oplus C^{\infty}\left(\partial_{-}\right)$, consisting of zonal harmonics. Hence there exist $a_{j} \in \mathbb{C}$, not all zero, such that

$$
\begin{equation*}
\tau\left(a_{1} w_{1}+a_{2} w_{2}+a_{3} w_{3}\right)=0 \tag{2.49}
\end{equation*}
$$

It follows from Lemma 2.9 that

$$
\begin{equation*}
a_{1} w_{1}+a_{2} w_{2}+a_{3} w_{3}=0 \quad \text { on } M, \tag{2.50}
\end{equation*}
$$

contradicting the mutual orthogonality of the spaces $W_{j}$. This gives the desired conclusion (2.42), for $n \geq 3$. The proof for $n=2$ is a variant, somewhat like the proof for $n=2$ in Proposition 2.4.

## 3 Amplitude distribution asymptotics for spherical harmonics on $S^{2}$

As discussed in $\S 1, L^{2}\left(S^{2}\right)$ has an orthonormal basis consisting of the spherical harmonics

$$
\begin{equation*}
Y_{k}^{\ell}, \quad k \in \mathbb{Z}^{+}, \ell \in \mathbb{Z},|\ell| \leq k, \tag{3.1}
\end{equation*}
$$

given by (1.26)-(1.27), joint eigenfunctions for the operators $\Lambda$, given by (1.18), and $X_{1}$, described below (1.21):

$$
\begin{equation*}
\Lambda Y_{k}^{\ell}=k Y_{k}^{\ell}, \quad X_{1} Y_{k}^{\ell}=\ell Y_{k}^{\ell} \tag{3.2}
\end{equation*}
$$

We see from (1.26) that

$$
\begin{equation*}
\left|Y_{k}^{\ell}(\omega)\right|^{2}=\left|\alpha_{k \ell}\right|^{2}\left(1-\omega_{3}^{2}\right)^{|\ell|} P_{k}^{(|\ell|)}\left(\omega_{3}\right)^{2} \tag{3.3}
\end{equation*}
$$

and this is a zonal function. Here we examine the asymptotic behavior of

$$
\begin{equation*}
\int_{S^{2}} f(\omega)\left|Y_{k}^{\ell}(\omega)\right|^{2} d S(\omega)=\left(M_{f} Y_{k}^{\ell}, Y_{k}^{\ell}\right)_{L^{2}} \tag{3.4}
\end{equation*}
$$

when $f$ is a zonal function on $S^{2}$. We use methods of microlocal analysis, rather than an analysis of the special functions $P_{k}$.

To begin, given $A: L^{2}\left(S^{2}\right) \rightarrow L^{2}\left(S^{2}\right)$, we form

$$
\begin{equation*}
\Pi(A)=\frac{1}{2 \pi} \int_{0}^{2 \pi} e^{-i t \Lambda} A e^{i t \Lambda} d t \tag{3.5}
\end{equation*}
$$

Note that $\left\{e^{i t \Lambda}: t \in \mathbb{R}\right\}$ is periodic in $t$ of period $2 \pi$, and $\Pi(A)$ commutes with $e^{i t \Lambda}$ for all $t$. If

$$
\begin{equation*}
A \in O P S^{0}\left(S^{2}\right) \tag{3.6}
\end{equation*}
$$

has principal symbol $a \in C^{\infty}\left(S^{*} S^{2}\right)$, then Egorov's theorem gives

$$
\begin{equation*}
\Pi(A)-\mathrm{op}(P a) \in O P S^{-1}\left(S^{2}\right) \tag{3.7}
\end{equation*}
$$

where $P a \in C^{\infty}\left(S^{*} S^{2}\right)$ is given by

$$
\begin{equation*}
P a(x, \xi)=\frac{1}{2 \pi} \int_{0}^{2 \pi} a\left(\mathcal{G}_{t}(x, \xi)\right) d t \tag{3.8}
\end{equation*}
$$

$\left\{\mathcal{G}_{t}: t \in \mathbb{R}\right\}$ denoting the Hamilton flow on $S^{*} S^{2}$ corresponding to the geodesic flow, which is also periodic of period $2 \pi$, and

$$
\begin{equation*}
\text { op : } C^{\infty}\left(S^{*} S^{2}\right) \longrightarrow O P S^{0}\left(S^{2}\right) \tag{3.9}
\end{equation*}
$$

is given by an appropriate quantization procedure.
Now we specialize to

$$
\begin{equation*}
A u=f u, \quad f \in C^{\infty}\left(S^{2}\right), \text { zonal. } \tag{3.10}
\end{equation*}
$$

Then $\Pi(A)$ also commutes with $R(t)=e^{i t X_{1}}$, for all $t$. Consequently, for $A$ of the form (3.10),

$$
\begin{equation*}
\Pi(A) \text { commutes with both } \Lambda \text { and } X_{1} \text {. } \tag{3.11}
\end{equation*}
$$

Given that $\operatorname{Spec}\left(\Lambda, X_{1}\right)$ is simple, it follows that $\Pi(A)$ has the form

$$
\begin{equation*}
\Pi(A)=F\left(\Lambda, X_{1}\right) \tag{3.12}
\end{equation*}
$$

Since we also know that $\Pi(A)$ is a pseudodifferential operator and we have a formula for its principal symbol, we can deduce information about the function $F$, using results on functional calculus for commuting self-adjoint pseudodifferential operators given in [9] and in Chapter 12 of [10] (see also [8] and [2], for related developments). These results yield

$$
\begin{equation*}
F \in S^{0}\left(\mathbb{R}^{2}\right) \Longrightarrow F\left(\Lambda, X_{1}\right)=B \in O P S^{0}\left(S^{2}\right) \tag{3.13}
\end{equation*}
$$

with principal symbol

$$
\begin{equation*}
b(x, \xi)=F(|\xi|,\langle Y, \xi\rangle) \tag{3.14}
\end{equation*}
$$

where $Y=i X_{1}$ is the real vector field generating rotation about the $x_{3}$-axis (of period $2 \pi$ ). Note that it suffices to specify $F$ on

$$
\left\{\left(\lambda_{1}, \lambda_{2}\right): \lambda_{1} \geq 0,\left|\lambda_{2}\right| \leq \lambda_{1}\right\}
$$

in light of the identification of $\operatorname{Spec}\left(\Lambda, X_{1}\right)$, and taking into account that $|Y| \leq 1$ on $S^{2}$. We want the principal part of (3.14) to match up with (3.8) on $S^{*} S^{2}$.

In light of this, we are motivated to define $F_{0}\left(\lambda_{1}, \lambda_{2}\right)$, homogeneous of degree 0 in $\left(\lambda_{1}, \lambda_{2}\right)$, so that

$$
\begin{equation*}
F_{0}(1,\langle Y, \xi\rangle)=P a(x, \xi) \text { for }(x, \xi) \in S^{*} S^{2} \tag{3.15}
\end{equation*}
$$

Now $F_{0}\left(1, \lambda_{2}\right)$ is a function of $\lambda_{2} \in[-1,1]$, while $P a$ is a function on $S^{*} S^{2}$, which has dimension 3. However, $P a$ is invariant under the flows $\mathcal{G}_{t}$ and $\mathcal{F}_{Y}^{t}$ (the flow generated by $Y$ ), and in fact it is uniquely specified by its behavior on $S_{x_{0}}^{*} S^{2}$, where $x_{0}$ is an arbitrarily chosen point on the equator of $S^{2}$. At $x_{0}, Y$ is a unit vector tangent to the equator, and (3.15) becomes

$$
\begin{equation*}
F_{0}\left(1, \lambda_{2}\right)=P a\left(x_{0},\left(\lambda_{2}, \sqrt{1-\lambda_{2}^{2}}\right)\right) \tag{3.16}
\end{equation*}
$$

At first glance, this looks non-smooth at $\lambda_{2}= \pm 1$, but in fact we have

$$
\begin{equation*}
P a\left(x_{0},\left(\xi_{1}, \xi_{2}\right)\right)=P a\left(x_{0},\left(\xi_{1},-\xi_{2}\right)\right) . \tag{3.17}
\end{equation*}
$$

Such an identity is clear if $f(x)$ is even under $x_{3} \mapsto-x_{3}$. On the other hand, if $f(x)$ is odd under this transformation its invariance under $R(t)$ guarantees that (3.8) vanishes, so we have (3.17) for general $R(t)$-invariant $f \in C^{\infty}\left(S^{2}\right)$. From (3.17) we have that (3.16) defines a smooth function of $\lambda_{2} \in[-1,1]$. We have the following conclusion.

Proposition 3.1 Let $f \in C^{\infty}\left(S^{2}\right)$ be a zonal function and let $A=M_{f}$, as in (3.10). Define Pa as in (3.8), with $a(x, \xi)=f(x)$. Then there exists $F_{0} \in S^{0}\left(\mathbb{R}^{2}\right)$ so that (3.15)-(3.16) hold, for $\left|\lambda_{2}\right| \leq 1$, and we have

$$
\begin{align*}
& F_{0}\left(\Lambda, X_{1}\right) \in O P S^{0}\left(S^{2}\right), \quad \text { and } \\
& \Pi(A)-F_{0}\left(\Lambda, X_{1}\right)=R \in O P S^{-1}\left(S^{2}\right) \tag{3.18}
\end{align*}
$$

Note that we have

$$
\begin{equation*}
F_{0}\left(\Lambda, X_{1}\right)=g\left(\Lambda^{-1} X_{1}\right), \tag{3.19}
\end{equation*}
$$

where $g(\lambda)=F_{0}(1, \lambda)$, for $|\lambda| \leq 1$, i.e.,

$$
\begin{equation*}
g(\lambda)=P a\left(x_{0},\left(\lambda, \sqrt{1-\lambda^{2}}\right)\right) . \tag{3.20}
\end{equation*}
$$

We return to (3.4) and write

$$
\begin{align*}
\int_{S^{2}} f(\omega)\left|Y_{k}^{\ell}(\omega)\right|^{2} d S(\omega) & =\left(A Y_{k}^{\ell}, Y_{k}^{\ell}\right)  \tag{3.21}\\
& =\left(\Pi(A) Y_{k}^{\ell}, Y_{k}^{\ell}\right) \\
& =\left(F_{0}\left(\Lambda, X_{1}\right) Y_{k}^{\ell}, Y_{k}^{\ell}\right)+\left(R Y_{k}^{\ell}, Y_{k}^{\ell}\right)
\end{align*}
$$

hence

$$
\begin{equation*}
\int_{S^{2}} f(\omega)\left|Y_{k}^{\ell}(\omega)\right|^{2} d S(\omega)=g\left(\frac{\ell}{k}\right)+R_{k \ell} \tag{3.22}
\end{equation*}
$$

with $g(\lambda)$ given by (3.20), and

$$
\begin{equation*}
R_{k \ell}=\left(R Y_{k}^{\ell}, Y_{k}^{\ell}\right)=\frac{1}{k}\left(R \Lambda Y_{k}^{\ell}, Y_{k}^{\ell}\right) \tag{3.23}
\end{equation*}
$$

hence

$$
\begin{equation*}
\left|R_{k \ell}\right| \leq \frac{1}{k}\|R \Lambda\|_{\mathcal{L}\left(L^{2}\right)}, \quad R \Lambda \in O P S^{0}\left(S^{2}\right) \tag{3.24}
\end{equation*}
$$

We can combine (3.22)-(3.24) with Corollary 2.2 to obtain the following.

Proposition 3.2 Assume $u \in V_{k}$, i.e., $\Lambda u=k u$, so

$$
\begin{equation*}
u=\sum_{|\ell| \leq k} a_{\ell} Y_{k}^{\ell} . \tag{3.25}
\end{equation*}
$$

Let $f \in C^{\infty}\left(S^{2}\right)$ be a zonal function, as in Proposition 3.1. Then

$$
\begin{equation*}
\int_{S^{2}} f(\omega)|u(\omega)|^{2} d S(\omega)=\sum_{|\ell| \leq k}\left|a_{\ell}\right|^{2} g\left(\frac{\ell}{k}\right)+R_{k}(u), \tag{3.26}
\end{equation*}
$$

with $g$ as described in Proposition 3.1, and

$$
\begin{equation*}
\left|R_{k}(u)\right| \leq \frac{C}{k}\|u\|_{L^{2}}^{2}, \quad C=\|R \Lambda\|_{\mathcal{L}\left(L^{2}\right)} . \tag{3.27}
\end{equation*}
$$

We give a geometrical perspective on how the function $g \in C^{\infty}([-1,1])$ depends on the zonal function $f \in C^{\infty}\left(S^{2}\right)$. Pick a point on the equator of $S^{2}$, say $x_{0}=(1,0,0) \in S^{2} \subset \mathbb{R}^{3}$. We have natural identifications of $T_{x_{0}} S^{2}, T_{x_{0}}^{*} S^{2}$, the ( $x_{1}, x_{3}$ )-plane, and $\mathbb{R}^{2}$. Given

$$
\begin{equation*}
\lambda \in[-1,1], \text { take } v=\left(\lambda, \sqrt{1-\lambda^{2}}\right) \in S^{1} \subset \mathbb{R}^{2} . \tag{3.28}
\end{equation*}
$$

Let $\gamma$ be the unit speed geodesic through $x_{0}$, with initial velocity $v$. This is a "great circle," of circumference $2 \pi$, starting and ending at $x_{0}$. Then

$$
\begin{equation*}
g(\lambda)=\text { mean value of }\left.f\right|_{\gamma} . \tag{3.29}
\end{equation*}
$$

Under these circumstances, we see that

$$
\begin{equation*}
\gamma(t)=\left(\cos t, \lambda \sin t, \sqrt{1-\lambda^{2}} \sin t\right) \tag{3.30}
\end{equation*}
$$

If we (pedantically) set $f(\omega)=f_{0}\left(\omega_{3}\right)$, then

$$
\begin{equation*}
g(\lambda)=\frac{1}{\pi} \int_{-\pi / 2}^{\pi / 2} f_{0}\left(\sqrt{1-\lambda^{2}} \sin t\right) d t \tag{3.31}
\end{equation*}
$$

Recovering a smoothness argument made above, we see that, if

$$
\begin{equation*}
f_{0}(s)=f_{1}\left(s^{2}\right)+s f_{2}\left(s^{2}\right), \quad s \in[-1,1], \tag{3.32}
\end{equation*}
$$

then

$$
\begin{equation*}
g(\lambda)=\frac{1}{\pi} \int_{-\pi / 2}^{\pi / 2} f_{1}\left(\left(1-\lambda^{2}\right) \sin ^{2} t\right) d t \tag{3.33}
\end{equation*}
$$

Returning to (3.31), we make a change of variable and write

$$
\begin{equation*}
g(\lambda)=\frac{1}{\pi} \int_{-1}^{1} f_{0}\left(\sqrt{1-\lambda^{2}} s\right) \frac{d s}{\sqrt{1-s^{2}}} \tag{3.34}
\end{equation*}
$$

The extreme cases are

$$
\begin{equation*}
g(0)=\frac{1}{\pi} \int_{-1}^{1} f_{0}(s) \frac{d s}{\sqrt{1-s^{2}}}, \quad g( \pm 1)=f_{0}(0) \tag{3.35}
\end{equation*}
$$

In these cases, (3.22) yields, for smooth zonal functions $f$, first

$$
\begin{align*}
& \int_{S^{2}} f(\omega)\left|Y_{k}^{0}(\omega)\right|^{2} d S(\omega) \\
& =\frac{1}{\pi} \int_{-1}^{1} f_{0}(s) \frac{d s}{\sqrt{1-s^{2}}}+O\left(k^{-1}\right)  \tag{3.36}\\
& =\frac{1}{2 \pi^{2}} \int_{S^{2}} \frac{f(\omega)}{\sqrt{1-\omega_{3}^{2}}} d S(\omega)+O\left(k^{-1}\right),
\end{align*}
$$

which one can compare with the statement (1.34) about the upper envelope of $P_{k}(t)$. Second,

$$
\begin{equation*}
\int_{S^{2}} f(\omega)\left|Y_{k}^{k}(\omega)\right|^{2} d S(\omega)=f_{0}(0)+O\left(k^{-1}\right) \tag{3.37}
\end{equation*}
$$

which one can compare with the concentration analysis (1.37).
Going further, we can establish a version of (1.38). In fact, from (3.34), we see that, if $f$ is a smooth zonal function,

$$
\begin{align*}
& f(\omega)=0 \text { for }\left|\omega_{3}\right| \leq \beta \\
& \Longrightarrow g(\lambda)=0 \text { for } \sqrt{1-\lambda^{2}} \leq \beta \\
& \Longrightarrow \int_{S^{2}} f(\omega)\left|Y_{k}^{\ell}(\omega)\right|^{2} d S(\omega)=O\left(k^{-1}\right), \text { for } \frac{|\ell|}{k} \geq \sqrt{1-\beta^{2}}, \tag{3.38}
\end{align*}
$$

the latter implication by (3.22). A convenient choice of $f$ yields the following.
Proposition 3.3 Take $\beta \in(0,1), \delta>0$. Then

$$
\begin{equation*}
\left.\frac{|\ell|}{k} \geq \sqrt{1-\beta^{2}} \Longrightarrow \int_{\left|\omega_{3}\right| \geq \beta+\delta} \right\rvert\, Y_{k}^{\ell}\left(\left.\omega\right|^{2} d S(\omega) \leq \frac{C(\delta)}{k}\right. \tag{3.39}
\end{equation*}
$$

We will obtain sharper estimates, in more general settings, in $\S 4$.

## 4 Shadow regions for families of eigenfunctions

In this section we let $M$ be a compact, connected, $n$-dimensional Riemannian manifold, and assume $M$ has a nonzero Killing field, generating a 1parameter group of isometries of $M$. We will also make the hypothesis that

$$
\begin{equation*}
A_{0}=\min _{x \in M}|Y(x)|<\max _{x \in M}|Y(x)|=A_{1} . \tag{4.1}
\end{equation*}
$$

Possibly $A_{0}=0$. The operator $X=i Y$ is self adjoint and commutes with $\Lambda=\sqrt{-\Delta}$. If $\lambda \in \operatorname{Spec} \Lambda$, then the $\lambda$-eigenspace

$$
\begin{equation*}
V_{\lambda}=\left\{u \in C^{\infty}(M): \Lambda u=\lambda u\right\} \tag{4.2}
\end{equation*}
$$

splits into joint eigenspaces

$$
\begin{equation*}
V_{\lambda}=\bigoplus_{\mu \in \mathcal{A}_{\lambda}} V_{\lambda \mu}, \quad V_{\lambda \mu}=\left\{u \in V_{\lambda}: X u=\mu u\right\}, \tag{4.3}
\end{equation*}
$$

where $\mathcal{A}_{\lambda}=\left\{\mu: V_{\lambda \mu} \neq 0\right\}$. We have

$$
\begin{equation*}
\operatorname{Spec}(\Lambda, X)=\left\{(\lambda, \mu): \lambda \in \operatorname{Spec} \Lambda, \mu \in \mathcal{A}_{\lambda}\right\} \tag{4.4}
\end{equation*}
$$

Note that, if $u \in V_{\lambda \mu}$ and $\|u\|_{L^{2}}=1$, then

$$
\begin{align*}
\mu^{2} & =\|X u\|_{L^{2}}^{2} \leq A_{1}^{2}\|\nabla u\|_{L^{2}}^{2}=A_{1}^{2}(-\Delta u, u) \\
& =A_{1}^{2}\|\Lambda u\|_{L^{2}}^{2}=A_{1}^{2} \lambda^{2}, \tag{4.5}
\end{align*}
$$

i.e.,

$$
\begin{equation*}
\mu \in \mathcal{A}_{\lambda} \Longrightarrow|\mu| \leq A_{1} \lambda \tag{4.6}
\end{equation*}
$$

Now, given a bounded function $F: \operatorname{Spec}(\Lambda, X) \rightarrow \mathbb{R}$, we can define $F(\Lambda, X)$ on $L^{2}(M)$ by

$$
\begin{equation*}
F(\Lambda, X) u=F(\lambda, \mu) u, \quad \text { for } \quad u \in V_{\lambda \mu} . \tag{4.7}
\end{equation*}
$$

As shown in Chapter 12 of [10],

$$
\begin{equation*}
F \in S^{0}\left(\mathbb{R}^{2}\right) \Longrightarrow F(\Lambda, X) \in O P S^{0}(M) \tag{4.8}
\end{equation*}
$$

and its principal symbol is

$$
\begin{equation*}
\sigma_{F(\Lambda, X)}(x, \xi)=F(|\xi|,\langle Y, \xi\rangle) . \tag{4.9}
\end{equation*}
$$

We will concentrate on $F$ of the following form: $F \in C^{\infty}\left(\mathbb{R}^{2} \backslash 0\right)$, homogeneous 0 . Note that only its behavior on the wedge $\left\{(\lambda, \mu):|\mu| \leq A_{1} \lambda\right\}$ is significant for the behavior of $F(\Lambda, X)$. We set

$$
\begin{equation*}
g(\mu)=F(1, \mu), \quad \text { so } \quad F(\Lambda, X)=g\left(\Lambda^{-1} X\right) \tag{4.10}
\end{equation*}
$$

Note that only the behavior of $g$ on $\mu \in\left[-A_{1}, A_{1}\right]$ is significant.
Using this analysis of $F(\Lambda, X)$, we will study certain "shadow regions" $\Omega \subset M$, and families of unit-norm eigenvectors in $V_{\lambda \mu}$ whose restrictions to $\Omega$ decay rapidly as $\lambda \rightarrow \infty$. The shadow regions will have the form

$$
\begin{equation*}
\Omega_{A}=\{x \in M:|Y(x)| \leq A\}, \tag{4.11}
\end{equation*}
$$

where we take $A \in\left(A_{0}, A_{1}\right)$. To start, take

$$
\begin{equation*}
f \in C^{\infty}(M), \quad \operatorname{supp} f \subset \Omega_{A}, \quad A^{\prime}>A \tag{4.12}
\end{equation*}
$$

From (4.8)-(4.9) we obtain the following:

$$
\begin{align*}
g & \in C^{\infty}\left(\left[-A_{1}, A_{1}\right]\right), g(\mu)=0 \text { for }|\mu| \leq A^{\prime} \\
& \Longrightarrow \sigma_{F(\Lambda, X)}(x, \xi)=0, \quad \forall x \in \Omega_{A}, \xi \in T_{x}^{*} M  \tag{4.13}\\
& \Longrightarrow M_{f} g\left(\Lambda^{-1} X\right) \in O P S^{-1}(M) .
\end{align*}
$$

Under these circumstances, we have

$$
\begin{align*}
\int_{M} f\left|g\left(\Lambda^{-1} X\right) u\right|^{2} d V & =\left(M_{f} g\left(\Lambda^{-1} X\right) u, g\left(\Lambda^{-1} X\right) u\right)  \tag{4.14}\\
& \leq\left\|M_{f} g\left(\Lambda^{-1} X\right) u\right\|_{L^{2}}\left\|g\left(\Lambda^{-1} X\right) u\right\|_{L^{2}}
\end{align*}
$$

Since, for $u \in V_{\lambda \mu}$, we have

$$
\begin{equation*}
M_{f} g\left(\Lambda^{-1} X\right) u=\lambda^{-1} M_{f} g\left(\Lambda^{-1} X\right) \Lambda u \tag{4.15}
\end{equation*}
$$

and $M_{f} g\left(\Lambda^{-1} X\right) \Lambda \in O P S^{0}(M)$, we have the following conclusion:
Proposition 4.1 Under the hypotheses on $f$ and $g$ given in (4.12)-(4.13),

$$
\begin{equation*}
u \in V_{\lambda \mu} \Rightarrow g\left(\frac{\mu}{\lambda}\right) \int_{M} f|u|^{2} d V \leq \frac{C}{\lambda}\|u\|_{L^{2}}^{2} \tag{4.16}
\end{equation*}
$$

As it stands, this result generalizes Proposition 3.3. However, as advertised there, our real goal in this section is to produce a much sharper estimate. The foundation for this is the following improvement on the conclusion in (4.13).

Proposition 4.2 Under the hypotheses on $f$ and $g$ given in (4.12)-(4.13),

$$
\begin{equation*}
M_{f} g\left(\Lambda^{-1} X\right) \in O P S^{-\infty}(M) \tag{4.17}
\end{equation*}
$$

Having this result, we can replace (4.15) by

$$
\begin{equation*}
M_{f} g\left(\Lambda^{-1} X\right) u=\lambda^{-m} M_{f} g\left(\Lambda^{-1} X\right) \Lambda^{m} u \tag{4.18}
\end{equation*}
$$

(provided $u \in V_{\lambda \mu}$ ), with

$$
\begin{equation*}
M_{f} g\left(\Lambda^{-1} X\right) \Lambda^{m} \in O P S^{-\infty}(M) \tag{4.19}
\end{equation*}
$$

to conclude that, for each $m \in \mathbb{N}$,

$$
\begin{equation*}
\left\|M_{f} g\left(\Lambda^{-1} X\right) u\right\|_{C^{m}(M)} \leq C_{m} \lambda^{-m}\|u\|_{L^{2}}, \tag{4.20}
\end{equation*}
$$

yielding the following improvement of Proposition 4.1.
Proposition 4.3 Under the hypotheses on $f$ and $g$ given in (4.12)-(4.13), we have

$$
\begin{equation*}
u \in V_{\lambda \mu} \Rightarrow g\left(\frac{\mu}{\lambda}\right)\|f u\|_{C^{m}(M)} \leq \frac{C_{m}}{\lambda^{m}}\|u\|_{L^{2}}, \tag{4.21}
\end{equation*}
$$

for each $m \in \mathbb{N}$.
The content of Proposition 4.2 is that, under the stated hypotheses on $f$ and $g$, the total symbol of $F(\Lambda, X)=g\left(\Lambda^{-1} X\right)$ vanishes on $T^{*} \Omega_{A} \backslash 0$, not just the principal symbol. One approach would be to analyze the total symbol of $F(\Lambda, X)$ on $T^{*} M \backslash 0$, but we will pursue an alternative approach, making use of local elliptic regularity.

To proceed, pick $h \in C^{\infty}\left(\left[-A_{1}, A_{1}\right]\right)$ such that

$$
\begin{align*}
h(\mu)=1 & \text { for }|\mu| \leq A,  \tag{4.22}\\
0 & \text { for }|\mu| \geq A^{\prime} .
\end{align*}
$$

Now $\sigma_{h\left(\Lambda^{-1} X\right)}(x, \xi)=h(\langle Y(x), \xi /| \xi| \rangle)$, so

$$
\begin{equation*}
h\left(\Lambda^{-1} X\right) \in O P S^{0}(M) \text { is elliptic on } \Omega_{A} . \tag{4.23}
\end{equation*}
$$

Thus there exists $P \in O P S^{0}(M)$ such that $P h\left(\Lambda^{-1} X\right)$ is microlocally $I$ on a conic neighborhood of $T^{*} \Omega_{A} \backslash 0$, so

$$
\begin{equation*}
M_{f}-M_{f} P h\left(\Lambda^{-1} X\right)=R \in O P S^{-\infty}(M) \tag{4.24}
\end{equation*}
$$

so (since $g h \equiv 0$ )

$$
\begin{align*}
M_{f} g\left(\Lambda^{-1} X\right) & =M_{f} \operatorname{Ph}\left(\Lambda^{-1} X\right) g\left(\Lambda^{-1} X\right)+\operatorname{Rg}\left(\Lambda^{-1} X\right) \\
& =\operatorname{Rg}\left(\Lambda^{-1} X\right) \tag{4.25}
\end{align*}
$$

which belongs to $O P S^{-\infty}(M)$. This proves Proposition 4.2.

## 5 Weyl asymptotics for joint eigenfunctions

Take $M, \Lambda, X$ as in $\S 4$. For each $(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X)$, take an orthonormal basis

$$
\begin{equation*}
u_{\lambda \mu j} \in V_{\lambda \mu}, \quad 1 \leq j \leq d_{\lambda \mu}=\operatorname{dim} V_{\lambda \mu} \tag{5.1}
\end{equation*}
$$

Given $B \in O P S^{0}(M)$, there is the Weyl formula

$$
\begin{equation*}
\lim _{R \rightarrow \infty} \frac{1}{N(R)} \sum_{\lambda \leq R} \sum_{\mu \in \mathcal{A}_{\lambda}} \sum_{j \leq d_{\lambda \mu}}\left(B u_{\lambda \mu j}, u_{\lambda \mu j}\right)=\int_{S^{*} M} \sigma_{B}(x, \xi) d S(x, \xi) \tag{5.2}
\end{equation*}
$$

where $d S(x, \xi)$ denotes the Liouville measure on $S^{*} M$, normalized to have total mass 1 , and

$$
\begin{equation*}
N(R)=\operatorname{dim} \bigoplus_{\lambda \leq R} V_{\lambda}=\sum_{\lambda \leq R} \sum_{\mu \in \mathcal{A}_{\lambda}} d_{\lambda \mu} \tag{5.3}
\end{equation*}
$$

There is also the Weyl asymptotic formula

$$
\begin{equation*}
N(R) \sim C(M) R^{n}+O\left(R^{n-1}\right), \quad C(M)=\frac{V_{n}}{(2 \pi)^{n}} \operatorname{Vol}(M) \tag{5.4}
\end{equation*}
$$

where $V_{n}=\pi^{n / 2} / \Gamma(n / 2+1)$ is the volume of the unit ball in $\mathbb{R}^{n}$.
To obtain a variant of Proposition 3.2, we take

$$
\begin{equation*}
h \in C^{\infty}\left(\left[-A_{1}, A_{1}\right]\right), \quad f \in C^{\infty}(M) \tag{5.5}
\end{equation*}
$$

and set

$$
\begin{equation*}
B=M_{f} h\left(\Lambda^{-1} X\right) \in O P S^{0}(M) \tag{5.6}
\end{equation*}
$$

with principal symbol

$$
\begin{equation*}
\sigma_{B}(x, \xi)=f(x) h(\langle Y(x), \xi /| \xi| \rangle) \tag{5.7}
\end{equation*}
$$

to obtain the following.
Proposition 5.1 For $M, \Lambda, X$ as in §4, h, $f$ as in (5.5), we have

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N(R)} \sum_{\{(\lambda, \mu, j): \lambda \leq R\}} h\left(\frac{\mu}{\lambda}\right) \int_{M} f(x)\left|u_{\lambda \mu j}(x)\right|^{2} d V(x) \\
& =\int_{S^{*} M} f(x) h(\langle Y(x), \xi\rangle) d S(x, \xi) \tag{5.8}
\end{align*}
$$

The result (5.2) is typically established using heat equation asymptotics, which yield

$$
\begin{equation*}
\operatorname{Tr} B e^{t \Delta} \sim C_{1}(M)\left(\int_{S^{*} M} \sigma_{B} d S\right) t^{-n / 2}, \quad \text { as } t \searrow 0 \tag{5.9}
\end{equation*}
$$

together with a Tauberian theorem. Sharper results are obtained via a wave equation approach, presented in [6], which generated a large body of work. This yields an analysis of

$$
\begin{equation*}
\operatorname{Tr} B e^{i t \Lambda} \in \mathcal{D}^{\prime}(\mathbb{R}) \tag{5.10}
\end{equation*}
$$

as a distribution having an isolated singularity at $t=0$ (and typically other singularities, which for current purposes one arranges to ignore). One obtains the following result. Take

$$
\begin{equation*}
\varphi \in \mathcal{S}(\mathbb{R}), \quad \varphi \geq 0, \quad \operatorname{supp} \hat{\varphi} \subset(-r, r), \quad r<\operatorname{Inj} M \tag{5.11}
\end{equation*}
$$

where Inj $M$ denotes the injectivity radius of $M$. Then, making use of

$$
B \varphi(\Lambda-R)=\int_{-\infty}^{\infty} B e^{i t(\Lambda-R)} \hat{\varphi}(t) d t
$$

one analyzes

$$
\operatorname{Tr} B \varphi(\Lambda-R)
$$

One obtains, in place of (5.2),

$$
\begin{equation*}
\lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda, \mu, j} \varphi(\lambda-R)\left(B u_{\lambda \mu j}, u_{\lambda \mu j}\right)=\int_{S^{*} M} \sigma_{B}(x, \xi) d S(x, \xi) \tag{5.12}
\end{equation*}
$$

where

$$
\begin{equation*}
N_{\varphi}(R)=\operatorname{Tr} \varphi(\Lambda-R)=\sum_{\lambda} \varphi(\lambda-R) \operatorname{dim} V_{\lambda}, \tag{5.13}
\end{equation*}
$$

which satisfies

$$
\begin{equation*}
N_{\varphi}(R) \sim C(\varphi, M) R^{n-1} . \tag{5.14}
\end{equation*}
$$

Taking $B$ as in (5.6), we have the following.
Proposition 5.2 For $M, \Lambda, X$ as in $\S 4, h, f$ as in (5.5), and $\varphi$ as in (5.11), we have

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu, j} h\left(\frac{\mu}{\lambda}\right) \int_{M} f(x)\left|u_{\lambda \mu j}(x)\right|^{2} d V(x) \\
& =\int_{S^{*} M} f(x) h(\langle Y(x), \xi\rangle) d S(x, \xi) . \tag{5.15}
\end{align*}
$$

Let us take a look at the following case, of 2 D surfaces of revolution, with a pole.

Corollary 5.3 In the setting of Proposition 5.2, assume in addition that

$$
\begin{equation*}
\operatorname{dim} M=2, \quad M \text { has a pole }, \quad \mathcal{F}_{Y}^{t} \text { has period } 2 \pi \tag{5.16}
\end{equation*}
$$

so

$$
\begin{equation*}
(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X) \Rightarrow \mu=\ell \in \mathbb{Z}, d_{\lambda \ell} \equiv 1 \tag{5.17}
\end{equation*}
$$

Then

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\ell} h\left(\frac{\ell}{\lambda}\right) \int_{M} f(x)\left|u_{\lambda \ell}(x)\right|^{2} d S(x) \\
& =\int_{S^{*} M} f(x) h(\langle Y(x), \xi\rangle) d S(x, \xi) . \tag{5.18}
\end{align*}
$$

We can interpret (5.18) as saying that, in an "averaged" sense, as $\lambda \rightarrow \infty$,

$$
\begin{equation*}
\sum_{\ell \in \mathcal{A}_{\lambda}} h\left(\frac{\ell}{\lambda}\right) \int_{M} f\left|u_{\lambda \ell}\right|^{2} d S \sim \operatorname{dim} V_{\lambda} \int_{S^{*} M} f(x) h(\langle Y(x), \xi\rangle) d S(x, \xi) . \tag{5.19}
\end{equation*}
$$

For comparison, in case $M=S^{2},(3.22)$ implies, for $\lambda=k \in \operatorname{Spec} \Lambda, k \rightarrow \infty$, and $f$ zonal,

$$
\begin{align*}
\sum_{\ell=-k}^{k} h\left(\frac{\ell}{k}\right) \int_{S^{2}} f\left|Y_{k}^{\ell}\right|^{2} d S & \sim \sum_{\ell=-k}^{k} h\left(\frac{\ell}{k}\right) g\left(\frac{\ell}{k}\right)  \tag{5.20}\\
& \sim \operatorname{dim} V_{k} \int_{-1}^{1} h(s) g(s) d s
\end{align*}
$$

with $g$ given by (3.20). We mention this here simply as a "heuristic," rather than something we will take further. But heuristics sometimes do lead to further interesting results.

We return to the general setting of Proposition 5.2 and take $f \equiv 1$, to obtain further information on the joint $\operatorname{spectrum} \operatorname{Spec}(\Lambda, X)$. We deduce from (5.15) that

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu \in \mathcal{A}_{\lambda}} h\left(\frac{\mu}{\lambda}\right) d_{\lambda \mu} \\
& =\int_{S^{*} M} h(\langle Y(x), \xi\rangle) d S(x, \xi) \tag{5.21}
\end{align*}
$$

To proceed, we write

$$
\begin{equation*}
\int_{S^{*} M} h(\langle Y(x), \xi\rangle) d S(x, \xi)=\int_{I} h(y) d \gamma(y), \quad I=\left[-A_{1}, A_{1}\right], \tag{5.22}
\end{equation*}
$$

where $\gamma$ is the push-forward of Liouville measure on $S^{*} M$ under the map

$$
\begin{equation*}
\sigma=\sigma_{X}: S^{*} M \longrightarrow I, \quad \sigma_{X}(x, \xi)=\langle Y(x), \xi\rangle . \tag{5.23}
\end{equation*}
$$

The following is a useful observation.
Lemma 5.4 The measure $\gamma$ is absolutely continuous with respect to Lebesgue measure on $I$, so

$$
\begin{equation*}
\int_{S^{*} M} h(\langle Y(x), \xi\rangle) d S(x, \xi)=\int_{I} h(y) \Psi(y) d y, \tag{5.24}
\end{equation*}
$$

with $\Psi$ (called the joint spectral clustering factor) satisfying

$$
\begin{equation*}
\Psi=\Psi_{M, X} \in L^{1}(I, d y), \quad \Psi \geq 0, \quad \int_{I} \Psi(y) d y=1 \tag{5.25}
\end{equation*}
$$

Proof. What is to be shown is that if $K \subset I$ is a Borel set,

$$
\begin{equation*}
\gamma(K)=0 \Longrightarrow \int_{\sigma^{-1}(K)} d S(x, \xi)=0 . \tag{5.26}
\end{equation*}
$$

Indeed, for each $x \in M$, we have $\sigma_{x}: S_{x}^{*} M \rightarrow \mathbb{R}$ given by $\sigma_{x}(\xi)=\langle Y(x), \xi\rangle$, and (if $\gamma(K)=0$ ) $\sigma_{x}^{-1}(K)$ has measure 0 in the $(n-1)$-sphere $S_{x}^{*} M$ for each $x$ for which $Y(x) \neq 0$, which is all but at most 2 values of $x$. The implication (5.26) then follows via Fubini's theorem.

From (5.21)-(5.24) we have

$$
\begin{align*}
& \lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu \in \mathcal{A}_{\lambda}} h\left(\frac{\mu}{\lambda}\right) d_{\lambda \mu} \\
& =\int_{I} h(y) d \gamma(y)=\int_{I} h(y) \Psi(y) d y, \tag{5.27}
\end{align*}
$$

for $h \in C^{\infty}(I)$. We want to extend this to a broader class of functions $h$. The extension to $h \in C(I)$ is easy enough, but we want to go further. To do this, suppose $h: I \rightarrow \mathbb{R}$ is bounded and that

$$
\begin{equation*}
h_{-} \leq h \leq h_{+}, \tag{5.28}
\end{equation*}
$$

where $h_{ \pm}$belong to a class $\mathcal{C}(I)$ of bounded, Borel functions on $I$ for which (5.27) is known to hold (with $h$ replaced by $h_{+}, h_{-}$). We deduce that

$$
\begin{align*}
& \limsup _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu \in \mathcal{A}_{\lambda}} h\left(\frac{\mu}{\lambda}\right) d_{\lambda \mu} \leq \int_{I} h_{+} d \gamma \\
& \liminf _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \sum_{\lambda} \varphi(\lambda-R) \sum_{\mu \in \mathcal{A}_{\lambda}} h\left(\frac{\mu}{\lambda}\right) d_{\lambda \mu} \geq \int_{I} h_{-} d \gamma . \tag{5.29}
\end{align*}
$$

This in turn yields the following.
Lemma 5.5 Let $h: I \rightarrow \mathbb{R}$ be a bounded function. Assume that, for each $\varepsilon>0$, there exist $h_{ \pm} \in \mathcal{C}(I)$ such that (5.28) holds and

$$
\begin{equation*}
\int_{I}\left(h_{+}-h_{-}\right) d \gamma<\varepsilon . \tag{5.30}
\end{equation*}
$$

then (5.27) holds for $h$.
If $h: I \rightarrow \mathbb{R}$ is bounded and, for each $\varepsilon>0$, there exist $h_{ \pm} \in C(I)$ such that (5.30) holds (in which case there exist $h_{ \pm} \in C^{\infty}(I)$ such that (5.30) holds), we say $h$ is Riemann integrable on the measured metric space $(I, \gamma)$, and write

$$
\begin{equation*}
h \in \mathcal{R}(I, \gamma) \tag{5.31}
\end{equation*}
$$

The content of Lemma 5.5 is that

$$
\text { (5.27) holds for } h \in \mathcal{R}(I, \gamma) \text {. }
$$

See Appendix A for a brief treatment of Riemann integrable functions on a compact measured metric space. The standard example, of course, is $\mathcal{R}(I)$, the space of Riemann integrable functions on a compact interval $I \subset \mathbb{R}$, in case $\gamma$ is Lebesgue measure. Our next goal is to establish:

Proposition 5.6 For $M, \Lambda, X$ as in Proposition 5.2, $f \in C^{\infty}(M)$, and $\varphi$ as in (5.11), we have (5.27) for all $h \in \mathcal{R}(I)$.

Proof. It remains only to prove that

$$
\begin{equation*}
\mathcal{R}(I) \subset \mathcal{R}(I, \gamma) \tag{5.32}
\end{equation*}
$$

when $\gamma$ is absolutely continuous with respect to Lebesgue measure. To do this, we use the fact that, for any finite Borel measure $\gamma$ on $I$, a bounded
function $h: I \rightarrow \mathbb{R}$ belongs to $\mathcal{R}(I, \gamma)$ if and only if the set of points in $I$ at which $h$ is discontinuous has $\gamma$-measure 0. See Proposition A.1. Since this characterization applies both to $\mathcal{R}(I, \gamma)$ and to $\mathcal{R}(I)$ (where it is classical), we have (5.32).

We next compute the functions $\Psi$ that arise in (5.24) and (5.27), in the two basic cases emphasized in the introduction.

Example 1. $M=\mathbb{T}^{2}$.
In this case, one has $S_{x}^{*} M$ canonically equivalent to the unit circle $S^{1} \subset \mathbb{R}^{2}$, for each $x \in \mathbb{T}^{2}$, and the push-forward of arc length on $S_{x}^{*} M$ under $\sigma_{x}$ is $2 / \sqrt{1-y^{2}} d y$. Hence, normalizing, we obtain

$$
\begin{equation*}
\Psi(y)=\frac{1}{\pi} \frac{1}{\sqrt{1-y^{2}}}, \quad y \in[-1,1] . \tag{5.33}
\end{equation*}
$$

Example 2. $M=S^{2}$.
In this case we have $S^{*} M=\left\{(x, \xi) \in S^{2} \times S^{2}: \xi \perp x\right\}$. This is naturally diffeomorphic to

$$
\begin{equation*}
S O(3)=\left\{X=(x, \xi, \eta) \in M(3, \mathbb{R}):(x, \xi) \in S^{*} M, \eta=x \times \xi\right\} \tag{5.34}
\end{equation*}
$$

The action of $S O(2)$ in $S^{*} M$ is given by

$$
(g, X) \mapsto g X, \quad X \in S O(3), \quad g=\left(\begin{array}{ccc}
\cos \theta & -\sin \theta &  \tag{5.35}\\
\sin \theta & \cos \theta & \\
& & 1
\end{array}\right) \in S O(2)
$$

We have a smooth map

$$
\begin{equation*}
\Xi: S^{*} M \longrightarrow S^{2} \tag{5.36}
\end{equation*}
$$

or equivalently

$$
\begin{equation*}
\Xi: S O(3) \longrightarrow S^{2}, \text { given by } \Xi(X)=X^{t} e_{3} \tag{5.37}
\end{equation*}
$$

where $e_{3}$ is the third standard basis vector of $\mathbb{R}^{3}$. Note that

$$
\begin{equation*}
g \in S O(2) \Longrightarrow \Xi(g X)=X^{t} g^{t} e_{3}=\Xi(X) \tag{5.38}
\end{equation*}
$$

so $\Xi$ induces a diffeomorphism

$$
\begin{equation*}
S O(2) \backslash S O(3) \longrightarrow S^{2} \tag{5.39}
\end{equation*}
$$

The explicit formula for $\Xi$ in (5.36) is

$$
\Xi(x, \xi)=\left(\begin{array}{c}
x^{t}  \tag{5.40}\\
\xi^{t} \\
\eta^{t}
\end{array}\right) e_{3}=\left(\begin{array}{c}
x \cdot e_{3} \\
\xi \cdot e_{3} \\
\eta \cdot e_{3}
\end{array}\right),
$$

where, recall, $\eta=x \times \xi$.
We seek a formula for $\sigma_{X}: S^{*} M \rightarrow \mathbb{R}$, given by $\sigma_{X}(x, \xi)=\langle Y(x), \xi\rangle$, that factors through (5.40). Note that, in this case, $M=S^{2}$, we have

$$
\begin{equation*}
Y(x)=e_{3} \times x \tag{5.41}
\end{equation*}
$$

hence

$$
\begin{equation*}
\sigma_{X}(x, \xi)=\left(e_{3} \times x\right) \cdot \xi=(x \times \xi) \cdot e_{3}=\eta \cdot e_{3}, \tag{5.42}
\end{equation*}
$$

so

$$
\begin{equation*}
\sigma_{X}(x, \xi)=\Xi(x, \xi) \cdot e_{3} \tag{5.43}
\end{equation*}
$$

Now $\Xi$ in (5.37) is measure-preserving, up to scaling. Furthermore, a classical area computation implies that the map

$$
\begin{equation*}
p_{3}: S^{2} \longrightarrow \mathbb{R}, \quad p_{3}(x)=x \cdot e_{3} \tag{5.44}
\end{equation*}
$$

pushes the standard area measure on $S^{2}$ onto Lebesgur measure on $[-1,1]$, up to scaling. We deduce that

$$
\begin{equation*}
\Psi(y)=\frac{1}{2}, \quad y \in[-1,1] . \tag{5.45}
\end{equation*}
$$

Remark. To make contact with formulas below, we find it convenient to permute variables in (5.40), and define

$$
\widetilde{\Xi}: S^{*} M \longrightarrow S^{2}, \quad \widetilde{\Xi}(x, \xi)=\left(\begin{array}{l}
\eta \cdot e_{3}  \tag{5.46}\\
\xi \cdot e_{3} \\
x \cdot e_{3}
\end{array}\right),
$$

so

$$
\begin{equation*}
\sigma_{X}(x, \xi)=\widetilde{\Xi}(x, \xi) \cdot e_{1} \tag{5.47}
\end{equation*}
$$

Having derived the formulas for the factor $\Psi(y)$ in Examples 1 and 2, we consider their significance in the formula (5.27) for joint spectral asymptotics of $(\Lambda, X)$ in these two cases. To begin, the formulas (5.33) and (5.45) are strikingly different. The first is singular at the endpoints of $[-1,1]$, while the second is simply constant along this whole interval. The singularities of $\Psi(y)$ in (5.33) provide a quantitative description of the clustering of points of $\operatorname{Spec}(\Lambda, X)$ at the edges $\mu= \pm \lambda$, in case $M=\mathbb{T}^{2}$, depicted in Figure 1.1. On the other hand, the flat graph of $\Psi(y)$ in (5.45) reflects the even distribution within $\{(\lambda, \mu):|\mu| \leq \lambda\}$ of points of $\operatorname{Spec}(\Lambda, X)$ for $M=S^{2}$, depicted in Figure 1.3.

## 6 Further examples, illustrating spectral clustering, concentration, and shadowing

In $\S 5$ we illustrated the spectral asymptotic result given in Proposition 5.6 by two examples, $M=\mathbb{T}^{2}$ and $M=S^{2}$. We turn to some further examples of types of surfaces of revolution in $\mathbb{R}^{3}$, giving rise to joint spectral clustering factors $\Psi(y)$ that exhibit various behaviors, ranging from smoothness on the entire interval $I=\left[-A_{1}, A_{1}\right]$ to cases with jumps and blowups, particularly $\log$ blowups, which are less severe than the blowup in (5.27). We will also make some comments on shadow regions and concentration regions for certain classes of joint eigenfunctions.

Example 3. More general convex surfaces of revolution.
Let $C$ be a simple, closed, smooth curve in the $\left(x_{1}, x_{3}\right)$-plane, symmetric about the $x_{3}$-axis and with positive curvature everywhere. Let $M$ be the surface of revolution in $\mathbb{R}^{3}$ obtained by rotating $C$ about the $x_{3}$-axis. See the left side of Figure 1.7 for an illustration. The surface $M$ has two poles. Translating and scaling, we will assume that they are at $e_{3}$ and $-e_{3}$. Under these hypotheses, there is a diffeomorphism $\psi: M \rightarrow S^{2}$, taking level curves of $\left.x_{3}\right|_{M}$ to level curves of $\left.x_{3}\right|_{S^{2}}$, commuting with the $S O(2)$ action of rotation about the $x_{3}$-axis. This gives rise to a diffeomorphism $\psi: T M \rightarrow T S^{2}$, linear on each fiber, hence (via the Riemannian metrics on $M$ and $S^{2}$ ) to a diffeomorphism $\psi: T^{*} M \rightarrow T^{*} S^{2}$, yielding in turn a diffeomorphism $\psi: S^{*} M \rightarrow S^{*} S^{2}$, commuting with the $S O(2)$-action (but in general not preserving Liouville measure). We can follow this with the diffeomorphism $S O(2) \backslash S^{*} S^{2} \rightarrow S^{2}$, discussed in Example 2, with the goal of analyzing $\sigma_{X}: S^{*} M \rightarrow \mathbb{R}$.

Actually, for this, it is more direct to proceed via the following observation. Let $C_{L}$ denote the left side of $C$ (where $\left.x_{1}<0\right)$. Pick $a=\left(a_{1}, 0, a_{3}\right)^{t} \in$ $C_{L}$, and consider $\xi \in S_{a}^{*} M$. (Use the inner product on $T_{a} M$ to identify $S_{a} M$ and $S_{a}^{*} M$.) We map the circle $S_{a}^{*} M$ onto the circle $\left\{x \in M: x_{3}=a_{3}\right\}$ so that $Y(a) /|Y(a)| \in S_{a} M \approx S_{a}^{*} M$ maps to $|Y(a)| e_{1}+a_{3} e_{3}$, and so that the map intertwines counterclockwise rotation in $T_{a}^{*} M$ with the $S O(2)$-action of rotation about the $x_{3}$ axis specified in (5.35). Call this map

$$
\begin{equation*}
\widetilde{\Xi}:\left.S^{*} M\right|_{C_{L}} \longrightarrow M . \tag{6.1}
\end{equation*}
$$

Using the diffeomorphism $\psi$ described above and the analysis in Example 2 , we have a smooth extension to

$$
\begin{equation*}
\widetilde{\Xi}: S^{*} M \longrightarrow M \tag{6.2}
\end{equation*}
$$

invariant under the $S O(2)$ action on $S^{*} M$, yielding a diffeomorphism $S O(2) \backslash$ $S^{*} M \rightarrow M$, and, extending (5.47),

$$
\begin{equation*}
\sigma_{X}(x, \xi)=\widetilde{\Xi}(x, \xi) \cdot e_{1} \tag{6.3}
\end{equation*}
$$

In the special case $M=S^{2}, \widetilde{\Xi}$ pushes Liouville measure on $S^{*} M$ onto area measure on $M$ (up to scaling). Generally, this might not hold, but the pushforward will be a smooth, positive multiple of area measure on $M$. We are hence in a position to use (6.3) to describe the behavior of the factor $\Psi(y)$. Indeed, the function $\Xi_{0}: M \rightarrow \mathbb{R}$ given by $\Xi_{0}(x)=x \cdot e_{1}$ is a Morse function, having two critical points, a nondegenerate minumum and a nondegenerate maximum, with critical values $-r_{1}$ and $r_{1}$, where

$$
\begin{equation*}
r_{1}=\left.\max x_{1}\right|_{C} \tag{6.4}
\end{equation*}
$$

We deduce that

$$
\begin{equation*}
\Psi \in C^{\infty}\left(\left[-r_{1}, r_{1}\right]\right), \quad \Psi>0 . \tag{6.5}
\end{equation*}
$$

This is a mild variation of the behavior in (5.45), and it leads to somewhat regular density of $\operatorname{Spec}(\Lambda, X)$ in $\left\{(\lambda, \mu):|\mu| \leq r_{1} \lambda\right\}$, without the sort of clustering arising for $\mathbb{T}^{2}$, as in Figure 1.1.

Example 4. Symmetric dumbbell.
Here we examine an example of a nonconvex surface of revolution, in which there is clustering of $\operatorname{Spec}(\Lambda, X)$. As in Example 3, we start with a simple, closed smooth curve $C$ in the ( $x_{1}, x_{3}$ )-plane, symmetric about the $x_{3}$-axis, and rotate it about the $x_{3}$-axis in $\mathbb{R}^{3}$ to produce a surface of revolution $M$. The difference here is that $C$ will not have curvature that is everywhere positive. We take $C$ as illustrated in Figure 6.1. We assume
the curvature of $C$ is nonzero

$$
\text { at } x_{1}= \pm r_{1} \text { and at } x_{1}= \pm r_{2} .
$$

We assume the left side $C_{L}$ of $C$ is the graph of $x_{1}=\beta\left(x_{3}\right), x_{3} \in[-1,1]$. In the example we consider here, $\beta\left(x_{3}\right)=\beta\left(-x_{3}\right)$, so $M$ has not only $S O(2)$ symmetry, but also the symmetry $\iota: M \rightarrow M$ given by

$$
\begin{equation*}
\iota\left(x_{1}, x_{2}, x_{3}\right)=\left(x_{1}, x_{2},-x_{3}\right) . \tag{6.6}
\end{equation*}
$$

Arguments from Example 3 extend, to produce a smooth map $\widetilde{\Xi}$, as in (6.2), invariant under the $S O(2)$ action on $S^{*} M$, yielding a diffeomorphism


Figure 6.1: Dumbbell figure with singular factor $\Psi(y)$ (Example 4)
$S O(2) \backslash S^{*} M \rightarrow M$, for which (6.3) holds. Again the qualitative features of the factor $\Psi(y)$ can be read off from how

$$
\begin{equation*}
\Xi_{0}: M \longrightarrow \mathbb{R}, \quad \Xi_{0}(x)=x \cdot e_{1} \tag{6.7}
\end{equation*}
$$

pushes forward the area element on $M$ to a measure on $\left[-r_{1}, r_{1}\right]$, with $r_{1}$ as in (6.4). The difference in this case is that $\Xi_{0}$ has more critical values. As before, we have $\pm r_{1}$ as maxima and minima of $\Xi_{0}$. This time, there are a pair of points in $M$ at which $\Xi_{0}=r_{1}$ and a pair of points at which $\Xi_{0}=-r_{1}$. These four points are nondegenerate critical points for $\Xi_{0}$. In addition, there are two points in $M$ at which $\Xi_{0}$ has a saddle, with critical values $\pm r_{2}$, as illustrated in Figure 6.1. One sees that the inverse images under $\Xi_{0}$ of $\left( \pm r_{2}, \pm r_{2}+\varepsilon\right)$ and $\left( \pm r_{2}-\varepsilon, \pm r_{2}\right)$ have area $\sim C \varepsilon \log \varepsilon$, so

$$
\begin{equation*}
\Psi(y) \sim C \log \frac{1}{\left|y \mp r_{2}\right|} \tag{6.8}
\end{equation*}
$$

for $y$ near $\pm r_{2}$. See the right side of Figure 6.1 for a depiction of the graph of $\Psi(y)$ in such a case. As a consequence

There is clustering of $\operatorname{Spec}(\Lambda, X)$ along the rays

$$
\begin{equation*}
\mu= \pm r_{2} \lambda, \text { as } \lambda \rightarrow \infty, \tag{6.9}
\end{equation*}
$$

though the clustering along these rays is less dense than it is along the rays $\mu= \pm \lambda$ for $M=\mathbb{T}^{2}$, as illustrated in Figure 1.1.
Remark. The result (6.8) assumes the curvature of $C$ is nonzero at $x_{1}=$ $\pm r_{2}$. If the curvature vanished at these points, $\Psi(y)$ would be have a stronger singularity at $y= \pm r_{2}$. Similarly, if the curvature of $C$ vanished at $x_{1}= \pm r_{1}$, $\Psi(y)$ would have a singularity at $y= \pm r_{1}$.

Continuing with Example 4, we now look at the part

$$
\begin{equation*}
\Sigma(A)=\left\{(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X):\left|\frac{\mu}{\lambda}\right| \geq A\right\} \tag{6.10}
\end{equation*}
$$

of the joint spectrum, for a given $A \in\left(r_{2}, r_{1}\right)$, and see that there is a bit of "spectral pairing" in this region of $\operatorname{Spec}(\Lambda, X)$. This is related to the eigenfunction concentration result of Proposition 4.3. To recall it, let us set

$$
\begin{align*}
\Omega_{A} & =\{x \in M:|Y(x)| \leq A\}  \tag{6.11}\\
& =\{x \in M: r(x) \leq A\},
\end{align*}
$$

where $r(x)=\left(x_{1}^{2}+x_{2}^{2}\right)^{1 / 2}$, and take

$$
\begin{equation*}
f \in C^{\infty}(M), \quad \operatorname{supp} f \subset \Omega_{A} . \tag{6.12}
\end{equation*}
$$

Proposition 4.3 implies the following result.

Proposition 6.1 In the current setting (Example 4), if $f$ satisfies (6.12), with $A \in\left(r_{2}, r_{1}\right)$, then

$$
\begin{align*}
& u \in V_{\lambda \mu}, \quad(\lambda, \mu) \in \Sigma\left(A^{\prime}\right), A^{\prime}>A \\
& \Longrightarrow\|f u\|_{C^{m}(M)} \leq \frac{C}{\lambda^{m}}\|u\|_{L^{2}}, \quad C=C_{m}\left(A, A^{\prime}\right) . \tag{6.13}
\end{align*}
$$

Let us now take $f$ satisfying (6.12) and also

$$
\begin{equation*}
Y f=0, \quad \iota^{*} f=f, \quad f \equiv 1 \text { on } \Omega_{B}, \text { for some } B \in\left(r_{2}, A\right) . \tag{6.14}
\end{equation*}
$$

We take $u$ as in (6.13), and set

$$
\begin{equation*}
v=(1-f) u \tag{6.15}
\end{equation*}
$$

so $v=0$ on a neighborhood of the "neck," $\left\{x \in M: r(x)=r_{2}\right\}$. It follows that

$$
\begin{equation*}
\left(-\Delta-\lambda^{2}\right) v=w, \quad\|w\|_{L^{2}} \leq \frac{c_{m}}{\lambda^{m}}\|u\|_{L^{2}} \tag{6.16}
\end{equation*}
$$

while

$$
\begin{equation*}
X v=\mu v . \tag{6.17}
\end{equation*}
$$

We can rewrite (6.16) as

$$
\begin{equation*}
(\Lambda-\lambda) v=w_{0}=(\Lambda+\lambda)^{-1} w, \quad\left\|w_{0}\right\|_{L^{2}} \leq \frac{c_{m}}{\lambda^{m+1}}\|u\|_{L^{2}} \tag{6.18}
\end{equation*}
$$

The function $v$ decouples into two pieces with disjoint support:

$$
\begin{equation*}
v=v_{+}+v_{-}, \quad \operatorname{supp} v_{ \pm} \subset\left\{x \in M: \pm x_{3}>0\right\} \tag{6.19}
\end{equation*}
$$

and $v_{+}$and $v_{-}$separately satisfy conditions of the form (6.16)-(6.18). Since $M$ has a pole, we have from Proposition 2.4 that

$$
\begin{equation*}
(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X) \Longrightarrow \operatorname{dim} V_{\lambda \mu}=1 \tag{6.20}
\end{equation*}
$$

so

$$
\begin{equation*}
u \in V_{\lambda \mu} \Longrightarrow \iota^{*} u=u \text { or } \iota^{*} u=-u \tag{6.21}
\end{equation*}
$$

Whatever parity $u$ has under $\iota^{*}, v$ in (6.15) has the same parity, so

$$
\begin{equation*}
u^{\#}=v_{+}-v_{-} \tag{6.22}
\end{equation*}
$$

has the opposite parity. This also satisfies conditions like (6.16)-(6.18), i.e.,

$$
\begin{equation*}
X u^{\#}=\mu u^{\#}, \quad(\Lambda-\lambda) u^{\#}=w_{0}^{\#}, \quad\left\|w_{0}^{\#}\right\|_{L^{2}} \leq \frac{c_{m}}{\lambda^{m+1}}\left\|u^{\#}\right\|_{L^{2}} . \tag{6.23}
\end{equation*}
$$

A function that satisfies (6.18) is called a $\lambda$-quasimode of $\Lambda$. If it also satisfies (6.17), we say it is a joint $(\lambda, \mu)$-quasimode of $(\Lambda, X)$. What is established above is that if $u \in V_{\lambda \mu}$, then the functions $v_{+}, v_{-}$, and $u^{\#}$ produced in (6.19) and (6.22) are all joint $(\lambda, \mu)$-quasimodes of $(\Lambda, X)$. As noted above, every joint eigenfunction is either even or odd with respect to $\iota^{*}$, so it is clear that neither of the quasimodes $v_{+}$or $v_{-}$is close to an actual joint eigenfunction.

To proceed, it is convenient to set up some notation. Set

$$
\begin{align*}
L_{\alpha}^{2}(M) & =\left\{u \in L^{2}(M): \iota^{*} u=\alpha u\right\}, \quad \alpha \in\{1,-1\}, \\
\operatorname{Spec}_{\alpha}(\Lambda, X) & =\left\{(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X): V_{\lambda \mu} \subset L_{\alpha}^{2}(M)\right\},  \tag{6.24}\\
\Sigma_{\alpha}(M) & =\Sigma(A) \cap \operatorname{Spec}_{\alpha}(\Lambda, X) .
\end{align*}
$$

Note that $\Sigma_{\alpha}(A) \cap \Sigma_{-\alpha}(A)=\emptyset$. We will establish the following.
Proposition 6.2 In the current setting (Example 4), given $A \in\left(r_{2}, r_{1}\right)$, $m \in \mathbb{N}$, there exist $L, C$ such that

$$
\begin{align*}
& \text { for }(\lambda, \mu) \in \Sigma_{\alpha}(X), \lambda \geq L, \alpha \in\{1,-1\}, \\
& \operatorname{dist}\left((\lambda, \mu), \operatorname{Spec}_{-\alpha}(\Lambda, X)\right) \leq \frac{C}{\lambda^{m}} \tag{6.25}
\end{align*}
$$

Proof. Let us denote by $\Lambda_{\alpha}$ the restriction of $\Lambda$ to $H^{1}(M) \cap L_{\alpha}^{2}(M)$, an unbounded self-adjoint operator on the Hilbert space $L_{\alpha}^{2}(M)$, as is $X$. Their joint spectrum is $\operatorname{Spec}_{\alpha}(\Lambda, X)$. Given that $u \in V_{\lambda \mu} \subset L_{\alpha}^{2}(M)$, the construction above produces $u^{\#} \in \mathcal{D}\left(\Lambda_{-\alpha}\right)$ such that (6.23) holds. Hence

$$
\begin{equation*}
\left\|\left(\Lambda_{-\alpha}-\lambda\right)^{-1}\right\| \geq \frac{1}{c_{m}} \lambda^{m+1} . \tag{6.26}
\end{equation*}
$$

Now the spectral theorem implies

$$
\begin{equation*}
\operatorname{dist}\left(\lambda, \operatorname{Spec} \Lambda_{-\alpha}\right)=\left\|\left(\Lambda_{-\alpha}-\lambda\right)^{-1}\right\|^{-1} \tag{6.27}
\end{equation*}
$$

so we have (6.25).

Example 5. Top-heavy dumbbell.
This example is similar to Example 4, except that now the surface does not have the symmetry (6.6). One starts with a curve $C$ in the ( $x_{1}, x_{3}$ )-plane, symmetric about the $x_{3}$-axis, as before, and assumes the left half $C_{L}$ is the


Figure 6.2: Top-heavy dumbbell figure and its factor $\Psi(y)$ (Example 5)
graph of $x_{1}=\beta\left(x_{3}\right)$, for $x_{3} \in[-1,1]$, but we do not have $\beta\left(x_{3}\right)=\beta\left(-x_{3}\right)$. Rather, this time, the appearance is as illustrated in Figure 6.2. We assume
the curvature of $C$ is nonzero

$$
\text { at } x_{1}= \pm r_{1}, \pm r_{2} \text { and } \pm r_{3} .
$$

Arguments used in Example 4 show that the qualitative features of the factor $\Psi(y)$ can be read off from how

$$
\begin{equation*}
\Xi_{0}: M \longrightarrow \mathbb{R}, \quad \Xi_{0}(x)=x \cdot e_{1} \tag{6.28}
\end{equation*}
$$

pushes forward the area element of $M$ to a measure on $\left[-r_{1}, r_{1}\right]$. Again, $\Xi_{0}$ has $\pm r_{1}$ as maxima and minima. This time, $\pm r_{2}$ are local maxima and minima, and there are two points in $M$ at which $\Xi_{0}$ has a saddle, with critical values $\pm r_{3}$. All 6 critical points are nondegenerate. The local max and min yield jumps in $\Psi(y)$ at $y= \pm r_{2}$, and the saddles yield $\log$ blowups of $\Psi(y)$ at $y= \pm r_{3}$, as illustrated in Figure 6.2.

We next examine concentration of eigenfunctions, using the sets

$$
\Sigma(A) \subset \operatorname{Spec}(\Lambda, X), \quad \Omega_{A} \subset M
$$

defined in (6.10)-(6.11). Arguing as in Example 4, we have again the conclusion of Proposition 6.1, which we restate:

Proposition 6.3 In the current setting (Example 5), given $A \in\left(r_{2}, r_{1}\right)$, we have

$$
\begin{align*}
& u \in V_{\lambda \mu}, \quad(\lambda, \mu) \in \Sigma\left(A^{\prime}\right), A^{\prime}>A \\
& \Longrightarrow\|u\|_{C^{m}\left(\Omega_{A}\right)} \leq \frac{C}{\lambda^{m}}\|u\|_{L^{2}}, \quad C=C_{m}\left(A, A^{\prime}\right) \tag{6.29}
\end{align*}
$$

Note that, for $A$ close to $r_{1}$, the concentration set $M \backslash \Omega_{A}$ is a small strip about the curve

$$
\begin{equation*}
\left\{x \in M: r(x)=r_{1}\right\}, \tag{6.30}
\end{equation*}
$$

which is a closed, elliptic geodesic. By contrast, in Example 4 the concentration set (6.30) consisted of a pair of closed, elliptic geodesics. We saw in that case that eigenfunctions could not concentrate on just one of these geodesics. Now, in Example 5, there is a family of eigenfunctions concentrating on the one closed geodesic given by (6.30). On the other hand, in Example 5, the set

$$
\begin{equation*}
\left\{x \in M: r(x)=r_{2}\right\} \tag{6.31}
\end{equation*}
$$

is also a closed, eliptic geodesic. It follows that there is a sequence of quasimodes that concentrate on this set (cf. [1]). Actually, in this case, one can cut and paste quasimodes that arise in Example 4. In light of other results holding for Example 4, we speculate that there is not a sequence of actual joint eigenfunctions that concentrate on the set (6.31). This might motivate further study.

In Example 4, the set described by (6.31) was a hyperbolic closed geodesic. Here in Example 5, the set

$$
\begin{equation*}
\left\{x \in M: r(x)=r_{3}\right\} \tag{6.32}
\end{equation*}
$$

is our hyperbolic closed geodesic.
Example 6. Surface with inflective invariant geodesic.
Here one starts with a smooth curve $C$ in the ( $x_{1}, x_{3}$ )-plane, symmetric about the $x_{3}$-axis, whose curvature vanishes simply, at two points, say ( $\pm r_{2}, z_{0}$ ), such that $\pm r_{2}$ are critical values of the $x_{1}$-coordinate on $C$. See
the left half of Figure 6.3. As in the previous examples, the singularities in the factor $\Psi(y)$ can be read off from how the function $\Xi_{0}: M \rightarrow \mathbb{R}$ given by $\Xi_{0}(x)=x \cdot e_{1}$ pushes forward the area measure of $M$ to a measure on [ $-r_{1}, r_{1}$ ], where $r_{1}$ is the maximum value of $\Xi_{0}$, again a nondegenerate critical value. Again $\Psi(y)$ has a graph that looks somewhat like the graph on the right half of Figure 6.1, but this time the singularities of $\Psi$ at $y= \pm r_{2}$ are stronger. In fact, the area of the inverse image $\Xi_{0}^{-1}\left(\left[r_{2}, r_{2}+\varepsilon\right)\right)$ behaves essentially like $A_{+}(\varepsilon)$, where

$$
\begin{equation*}
A_{ \pm}(\varepsilon)= \pm \int_{0}^{1}\left\{\left(x^{2} \pm \varepsilon\right)^{1 / 3}-x^{2 / 3}\right\} d x \tag{6.33}
\end{equation*}
$$

One has

$$
\begin{equation*}
A_{+}^{\prime}(\varepsilon)=\frac{1}{3} \int_{0}^{1}\left(x^{2}+\varepsilon\right)^{-2 / 3} d x \sim C \varepsilon^{-1 / 6} \tag{6.34}
\end{equation*}
$$

and similarly for $A_{-}^{\prime}(\varepsilon)$, and hence

$$
\begin{equation*}
\Psi(y) \sim C\left|y \mp r_{2}\right|^{-1 / 6} \tag{6.35}
\end{equation*}
$$

for $y$ near $\pm r_{2}$. Again we have a conclusion similar to (6.9), namely clustering of $\operatorname{Spec}(\Lambda, X)$ along the rays $\mu= \pm r_{2} \lambda$, as $\lambda \rightarrow \infty$. This clustering is stronger than in Example 4, but not as pronounced as that along the rays $\mu= \pm \lambda$ in Example 1 (where $M=\mathbb{T}^{2}$ ).

Example 7. Inner tube.
The previous examples in this section all arose by taking a smooth closed curve $C$ in the ( $x_{1}, x_{3}$ )-plane that was symmetric about the $x_{3}$-axis, and rotating it about this axis in $\mathbb{R}^{3}$. By contrast, this example takes $C$ to be a smooth closed curve contained in the half-plane $\left\{x_{1}>0\right\}$, namely $C=C_{a b}$, the circle

$$
\begin{equation*}
C_{a b}=\left\{\left(x_{1}, x_{3}\right):\left(x_{1}-a\right)^{2}+x_{3}^{2}=b^{2}\right\}, \quad 0<b<a . \tag{6.36}
\end{equation*}
$$

Rotating this about the $x_{3}$-axis in $\mathbb{R}^{3}$ produces an "inner tube," somewhat like that pictured in the right half of Figure 1.7. We take

$$
r_{1}=a+b, \quad r_{2}=a-b .
$$

Again, looking at $\Xi_{0}: M \rightarrow \mathbb{R}$ defined as above, we see that $\Psi \in L^{1}\left(\left[-r_{1}, r_{1}\right]\right)$ is smooth except for logarithmic singularities at $y= \pm r_{2}$, as in (6.8). Thus we see how clustering of $\operatorname{Spec}(\Lambda, X)$ in this case occurs, but differs from that for the flat torus $M=\mathbb{T}^{2}$ described in Example 1.


Figure 6.3: Generating curves for the surfaces in Examples 6 and 7


Figure 6.4: Generating curves for the surfaces in Examples 8 and 9

Example 8. Surface with flattened equator.
Here the curve $C$ in the ( $x_{1}, x_{3}$ )-plane that we rotate about the $x_{3}$-axis is given by

$$
\begin{equation*}
x_{1}^{4}+\frac{x_{3}^{2}}{2}=1 . \tag{6.37}
\end{equation*}
$$

See the left half of Figure 6.4. The Gauss curvature of this surface is $>0$ everywhere except at the equator ( $x_{3}=0$ ), where it vanishes to second order. A calculation similar to that done for Example 6 yields $\Psi \in C^{\infty}((-1,1))$, blowing up at the endpoints,

$$
\begin{equation*}
\Psi(y) \sim C\left(1-y^{2}\right)^{-1 / 4}, \quad y \in(-1,1) . \tag{6.38}
\end{equation*}
$$

This blow-up is less severe than that arising for flat $\mathbb{T}^{2}$ in Example 1 (cf. (5.33)), but stronger than the blow-up at $y= \pm r_{2}$ in Example 6 (cf. (6.35)).

For $(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X)$, the joint eigenspace $V_{\lambda \mu}$ is one-dimensional, since $M$ has a pole. Also, in this case $M$ is invariant under the involution $x_{3} \mapsto-x_{3}$, so a joint eigenfunction in $V_{\lambda \mu}$ is either even or odd with respect to this involution.

We have the shadow phenomenon for elements of $V_{\lambda \mu}$, given $|\mu / \lambda| \geq$ $A, A \in(0,1)$, as described in Proposition 4.3. As $A \nearrow 1$, the joint eigenfunctions concentrate on the equator.

Example 9. Capped cylinder.
Here the curve $C$, illustrated in the right half of Figure 6.4, contains the line segments

$$
\begin{equation*}
x_{1}= \pm 1, \quad x_{3} \in[-1,1] . \tag{6.39}
\end{equation*}
$$

The resulting surface of revolution $M$ consists of a circular cylinder with two caps. The Gauss curvature of $M$ is positive on the caps, and zero on the cylinder. In this case we have $\Psi \in C^{\infty}((-1,1))$, blowing up at the endpoints at the same rate as in Example 1,

$$
\begin{equation*}
\Psi(y) \sim C\left(1-y^{2}\right)^{-1 / 2}, \quad y \in(-1,1) . \tag{6.40}
\end{equation*}
$$

Then $\operatorname{Spec}(\Lambda, X)$ exhibits clustering near $\mu= \pm \lambda$ in a fashion similar to that illustrated in Figure 1.1, though of course, unlike in that case, it cannot be expected to be arranged along hyperbolic arcs.

As in Example 7, if $(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X)$, then $V_{\lambda \mu}$ is one dimensional. Again we arrange that $M$ be invariant under the involution $x_{3} \mapsto-x_{3}$, so
eigenfunctions in such $V_{\lambda \mu}$ are either even or odd under this involution. Let us write

$$
\begin{equation*}
M=M_{+} \cup M_{0} \cup M_{-}, \tag{6.41}
\end{equation*}
$$

where $M_{ \pm}$are the top and bottom caps, and

$$
\begin{equation*}
M_{0}, \text { isometric to }[-1,1] \times \mathbb{R} / 2 \pi \mathbb{Z}, \tag{6.42}
\end{equation*}
$$

is the cylindrical part of $M$. Note that

$$
\begin{equation*}
\text { on } M_{0}, \quad \Delta=X^{2}+\partial_{x_{3}}^{2}, \tag{6.43}
\end{equation*}
$$

so, given $(\lambda, \mu) \in \operatorname{Spec}(\Lambda, X)$,

$$
\begin{align*}
u \in V_{\lambda \mu} & \Rightarrow\left(X^{2}+\partial_{x_{3}}^{2}\right) u=-\lambda^{2} u \\
& \Rightarrow \partial_{x_{3}}^{2} u=-\left(\lambda^{2}-\mu^{2}\right) u, \text { on } M_{0} \tag{6.44}
\end{align*}
$$

Hence

$$
\begin{equation*}
u \in V_{\lambda \mu} \Longrightarrow u=e^{i \mu \psi} v\left(x_{3}\right), \quad \text { on } M_{0} \tag{6.45}
\end{equation*}
$$

where $\psi$ is the angular coordinate on $M_{0}$, and

$$
\begin{equation*}
v^{\prime \prime}\left(x_{3}\right)=-\left(\lambda^{2}-\mu^{2}\right) v\left(x_{3}\right), \quad\left|x_{3}\right| \leq 1 . \tag{6.46}
\end{equation*}
$$

As we have seen, $v$ is either even or odd, so, for some $\alpha \in \mathbb{C}$,

$$
\begin{align*}
& v\left(x_{3}\right)=\alpha \cos \sqrt{\lambda^{2}-\mu^{2}} x_{3}, \quad \text { or } \\
& v\left(x_{3}\right)=\alpha \sin \sqrt{\lambda^{2}-\mu^{2}} x_{3}, \tag{6.47}
\end{align*}
$$

for $x_{3} \in[-1,1]$.
Again we have the shadow phenomenon for elements of $V_{\lambda \mu}$, given $|\mu / \lambda| \geq$ $A, A \in(0,1)$, as described in Proposition 4.3. If $\mathcal{O}$ is a fixed neighborhood if the cylinder $M_{0}$, then there exists $A<1$ with the property that such eigenfunctions vanish rapidly on $M \backslash \mathcal{O}$, as $\lambda \rightarrow \infty$.

## A Riemann integrable functions on a compact measured metric space

Let $X$ be a compact metric space, equipped with a finite Borel measure $\mu$. Let $f: X \rightarrow \mathbb{R}$ be bounded. We define

$$
\begin{align*}
& \bar{I}(f)=\inf \left\{\int_{X} v d \mu: v \geq f, v \in C(X)\right\}, \\
& \underline{I}(f)=\sup \left\{\int_{X} u d \mu: u \leq f, u \in C(X)\right\}, \tag{A.1}
\end{align*}
$$

where $C(X)$ denotes the space of continuous, real-valued functions on $X$. Clearly $\underline{I}(f) \leq \bar{I}(f)$. We say

$$
\begin{equation*}
f \in \mathcal{R}(X, \mu) \Longleftrightarrow \bar{I}(f)=\underline{I}(f) \tag{A.2}
\end{equation*}
$$

In case $X$ is a product of $n$ closed, bounded intervals in $\mathbb{R}^{n}$ and $\mu$ is Lebesgue measure, it is easy to show that (A.2) is equivalent to the standard definition of Riemann integrability, involving taking partitions; cf. [12], Proposition 3.1.11. The following is a generalization of Lebesgue's theorem characterizing Riemann integrability.

Proposition A. 1 Given $f: X \rightarrow \mathbb{R}$ bounded, set

$$
\begin{equation*}
\mathcal{D}_{f}=\{x \in X: f \text { not continuous at } x\} . \tag{A.3}
\end{equation*}
$$

Then $\mathcal{D}_{f}$ is a Borel subset of $X$, and

$$
\begin{equation*}
f \in \mathcal{R}(X, \mu) \Longleftrightarrow \mu\left(\mathcal{D}_{f}\right)=0 . \tag{A.4}
\end{equation*}
$$

To start the proof, we note that $C(X)$ is a separable Banach space, and let $\mathcal{E} \subset C(X)$ be a countable dense subset. Set

$$
\begin{array}{ll}
\mathcal{C}_{f}^{+}=\{v \in C(X): v \geq f\}, & \mathcal{E}_{f}^{+}=\{v \in \mathcal{E}: v \geq f\},  \tag{A.5}\\
\mathcal{C}_{f}^{-}=\{u \in C(X): u \leq f\}, & \mathcal{E}_{f}^{-}=\{u \in \mathcal{E}: u \leq f\} .
\end{array}
$$

Note that $\mathcal{E}_{f}^{+}$is dense in $\mathcal{C}_{f}^{+}$and $\mathcal{E}_{f}^{-}$is dense in $\mathcal{C}_{f}^{-}$. Then set

$$
\begin{align*}
& \psi=\inf \left\{v: v \in \mathcal{C}_{f}^{+}\right\}=\inf \left\{v: v \in \mathcal{E}_{f}^{+}\right\} \\
& \varphi=\sup \left\{u: u \in \mathcal{C}_{f}^{-}\right\}=\sup \left\{u: u \in \mathcal{E}_{f}^{-}\right\} . \tag{A.6}
\end{align*}
$$

Note that $\varphi \leq f \leq \psi$. Using countability, write

$$
\begin{equation*}
\mathcal{E}_{f}^{+}=\left\{v_{j}: j \in \mathbb{N}\right\}, \quad \mathcal{E}_{f}^{-}=\left\{u_{j}: j \in \mathbb{N}\right\} . \tag{A.7}
\end{equation*}
$$

Let

$$
\begin{equation*}
\psi_{j}=\min _{k \leq j} v_{k}, \quad \varphi_{j}=\max _{k \leq j} u_{k} . \tag{A.8}
\end{equation*}
$$

Then

$$
\begin{equation*}
\psi_{j} \in \mathcal{C}_{f}^{+}, \quad \varphi_{j} \in \mathcal{C}_{f}^{-} \tag{A.9}
\end{equation*}
$$

and these are bounded monotone sequences, so they converge at each point of $X$,

$$
\begin{equation*}
\psi_{j} \searrow \psi, \quad \varphi_{j} \nearrow \varphi, \tag{A.10}
\end{equation*}
$$

with $\psi$ and $\varphi$ as in (A.6). Thus $\psi$ and $\varphi$ are Borel functions, and the monotone convergence theorem implies

$$
\begin{equation*}
\int_{X} \psi_{j} d \mu \searrow \int_{X} \psi d \mu, \quad \int_{X} \varphi_{j} d \mu \nearrow \int_{X} \varphi d \mu . \tag{A.11}
\end{equation*}
$$

We see that if $v \in \mathcal{E}_{f}^{+}$then $\psi_{j} \leq v$ for $j$ sufficiently large, and if $u \in \mathcal{E}_{f}^{-}$ then $\varphi_{j} \geq u$ for $j$ sufficiently large. Also

$$
\begin{align*}
& \bar{I}(f)=\inf \left\{\int_{X} v d \mu: v \in \mathcal{C}_{f}^{+}\right\}=\inf \left\{\int_{X} v d \mu: v \in \mathcal{E}_{f}^{+}\right\},  \tag{A.12}\\
& \underline{I}(f)=\sup \left\{\int_{X} u d \mu: u \in \mathcal{C}_{f}^{-}\right\}=\sup \left\{\int_{X} u d \mu: u \in \mathcal{E}_{f}^{-}\right\} .
\end{align*}
$$

Thus, by (A.11),

$$
\begin{equation*}
\bar{I}(f)=\int_{X} \psi d \mu, \quad \underline{I}(f)=\int_{X} \varphi d \mu . \tag{A.13}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
\bar{I}(f)-\underline{I}(f)=\int_{X}(\psi-\varphi) d \mu . \tag{A.14}
\end{equation*}
$$

The next lemma brings in $\mathcal{D}_{f}$.
Lemma A. 2 Given $x \in X$, the function $f$ is continuous at $x$ if and only if $\varphi(x)=\psi(x)$.

Proof. It is equivalent to say $f$ is continuous at $x$ if and only if for each $\varepsilon>0, \exists$ continuous $u_{\varepsilon} \leq f$ and continuous $v_{\varepsilon} \geq f$ such that $v_{\varepsilon}(x)-u_{\varepsilon}(x)<\varepsilon$.

Indeed if (A.15) holds, then $x_{j} \rightarrow x$ implies

$$
\begin{equation*}
\limsup _{j \rightarrow \infty} f\left(x_{j}\right) \leq v_{\varepsilon}(x), \quad \liminf _{j \rightarrow \infty} f\left(x_{j}\right) \geq u_{\varepsilon}(x), \tag{A.16}
\end{equation*}
$$

so these differ by at most $\varepsilon$, for each $\varepsilon>0$, hence $f$ is continuous at $x$.
For the converse, if $|f| \leq M$ on $X$, and $f$ is continuous at $x$, then, given $\varepsilon>0$, there exists a ball $B_{\delta}(x)$ such that

$$
\begin{equation*}
y \in B_{\delta}(x) \Longrightarrow|f(x)-f(y)|<\frac{\varepsilon}{4} \tag{A.17}
\end{equation*}
$$

Then, assuming $\varepsilon<M$, we can define $v_{\varepsilon} \in C(X)$ by

$$
\begin{align*}
v_{\varepsilon}(y)= & f(x)+\frac{\varepsilon}{3}+\frac{4 M}{\delta} d(y, x), \quad y \in B_{\delta}(x),  \tag{A.18}\\
& f(x)+\frac{\varepsilon}{3}+4 M, \quad y \in X \backslash B_{\delta}(x),
\end{align*}
$$

and similarly define $u_{\varepsilon} \in C(X)$ so that (A.15) holds.
Having Lemma A.2, we see that

$$
\begin{equation*}
\mathcal{D}_{f}=\{x \in X: \varphi(x)<\psi(x)\} . \tag{A.19}
\end{equation*}
$$

This guarantees that $\mathcal{D}_{f}$ is a Borel subset of $X$, and (A.14) yields

$$
\begin{equation*}
\bar{I}(f)-\underline{I}(f)=\int_{\mathcal{D}_{f}}(\psi-\varphi) d \mu \tag{A.20}
\end{equation*}
$$

This proves Proposition A.1.
Furthermore, we see that if $f \in \mathcal{R}(X, \mu)$, then $f$ is equal to each of the Borel functions $\varphi$ and $\psi$, on the complement of a set of $\mu$-measure 0 . Hence $f$ is $\bar{\mu}$-measurable, where $\bar{\mu}$ is the completion of $\mu$. We deduce that

$$
\begin{equation*}
f \in \mathcal{R}(X, \mu) \Longrightarrow f \in L^{1}(X, \bar{\mu}) \text { and } \int_{X} f d \bar{\mu}=\bar{I}(f)=\underline{I}(f) \tag{A.21}
\end{equation*}
$$

## B Finite symmetry group actions on eigenspaces

Let $M$ be a compact, connected, $n$-dimensional Riemannian manifold, with Laplace operator $\Delta, \Lambda=\sqrt{-\Delta}$. Suppose $B \in O P S^{0}(M)$ is self adjoint and commutes with $\Lambda$. We also assume $K$ is a finite group of isometries of $M$. Let $\widehat{K}$ denote a complete set of irreducible unitary representations of $K$, and, for $\rho \in \widehat{K}$, consider $P_{\rho} \in \mathcal{L}\left(L^{2}(M)\right)$, given by

$$
\begin{equation*}
P_{\rho} u(x)=\frac{d_{\rho}}{\#(K)} \sum_{g \in K} \overline{\chi_{\rho}(g)} u\left(g^{-1} x\right), \tag{B.1}
\end{equation*}
$$

where $\chi_{\rho}(g)=\operatorname{Tr} \rho(g), d_{\rho}=\chi_{\rho}(I)$, and $\#(K)$ is the number of elements of $K$. Then $P_{\rho}$ is the orthogonal projection of $L^{2}(M)$ onto the subspace of $K$ on which $K$ acts like copies of $\rho$.

We are interested in the behavior of

$$
\begin{equation*}
P_{\rho} B \varphi(\Lambda-R), \tag{B.2}
\end{equation*}
$$

and its trace, as $R \rightarrow \infty$. As in $\S 5$, we assume

$$
\begin{equation*}
\varphi \in \mathcal{S}(\mathbb{R}), \quad \varphi \geq 0, \quad \operatorname{supp} \hat{\varphi} \subset(-\tau, \tau), \quad \tau<\operatorname{Inj} M \tag{B.3}
\end{equation*}
$$

To tackle (B.2), we define the integral kernel $\Phi_{B, R}(x, y)$ of $B \varphi(\Lambda-R)$ :

$$
\begin{equation*}
B \varphi(\Lambda-R) u(x)=\int_{M} \Phi_{B, R}(x, y) u(y) d V(y) . \tag{B.4}
\end{equation*}
$$

Then

$$
\begin{equation*}
P_{\rho} B \varphi(\Lambda-R) u(x)=\frac{d_{\rho}}{\#(K)} \sum_{g \in K} \overline{\chi_{\rho}(g)} \int_{M} \Phi_{B, R}\left(g^{-1} x, y\right) u(y) d V(y) . \tag{B.5}
\end{equation*}
$$

Consequently,

$$
\begin{align*}
\operatorname{Tr} P_{\rho} B \varphi(\Lambda-R)= & \frac{d_{\rho}^{2}}{\#(K)} \operatorname{Tr} B \varphi(\Lambda-R) \\
& +\frac{d_{\rho}}{\#(K)} \sum_{g \neq I} \overline{\chi_{\rho}(g)} \int_{M} \Phi_{B, R}\left(g^{-1} x, x\right) d V(x) . \tag{B.6}
\end{align*}
$$

In $\S 5$ we recalled that analysis in [6] of

$$
\begin{equation*}
B \varphi(\Lambda-R)=\int_{-\infty}^{\infty} B e^{i t \Lambda} e^{-i t R} \hat{\varphi}(t) d t \tag{B.7}
\end{equation*}
$$

yields

$$
\begin{equation*}
\operatorname{Tr} \varphi(\Lambda-R)=N_{\varphi}(R) \sim C(\varphi, M) R^{n-1}, \quad R \rightarrow \infty, \tag{B.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \operatorname{Tr} B \varphi(\Lambda-R)=\int_{S^{*} M} \sigma_{B}(x, \xi) d S(x, \xi), \tag{B.9}
\end{equation*}
$$

where $d S(x, \xi)$ is Liouville measure on $S^{*} M$, normalized to have total mass 1. Furthermore, an analysis of the Schwartz kernel $W_{t}(x, y)$ of $e^{i t \Lambda}$, for $|t|<\operatorname{Inj} M$, gives, for $g \neq I$,

$$
\begin{equation*}
\int_{M} \Phi_{B, R}\left(g^{-1} x, x\right) d V(x)=o\left(R^{n-1}\right), \quad R \rightarrow \infty . \tag{B.10}
\end{equation*}
$$

We have the following conclusion.
Proposition B. 1 In the setting described above,

$$
\begin{equation*}
\lim _{R \rightarrow \infty} \frac{1}{N_{\varphi}(R)} \operatorname{Tr} P_{\rho} B \varphi(\Lambda-R)=\frac{d_{\rho}^{2}}{\#(K)} \int_{S^{*} M} \sigma_{B}(x, \xi) d S(x, \xi) \tag{B.11}
\end{equation*}
$$

In connection with this result, we mention the classical result that

$$
\begin{equation*}
\sum_{\rho \in \widehat{K}} d_{\rho}^{2}=\#(K), \tag{B.12}
\end{equation*}
$$

and $d_{\rho}^{2} / \#(K)$ is the fraction of the finite dimensional Hilbert space $\ell^{2}(K)$ on which the regular representation of $K$ acts like copies of $\rho$.

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